Answer Set Programming in a Nutshell

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Outline

- 1 Introduction
- 2 Foundations
- 3 Modeling
- 4 Algorithms and Systems
- 5 Potassco
- 6 Summary



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Answer Set Programming (ASP)

- ASP is an approach to declarative problem solving
 - describe the problem, not how to solve it
- ASP allows for solving hard search and optimization problems
 - Systems Biology
 - Product Configuration
 - Linux Package Configuration
 - Robotics
 - Music Composition
 - **=** ...
- lacksquare All search-problems in NP (and NP^{NP}) are expressible



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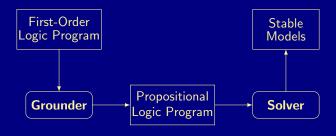
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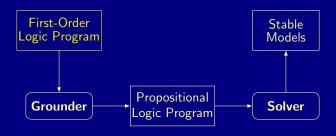
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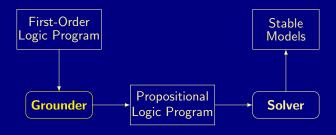
Expressive modeling language
Powerful grounding and solving tools





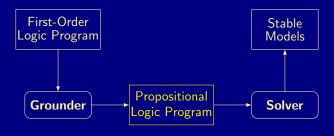
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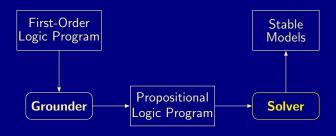
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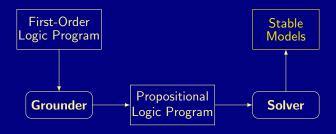
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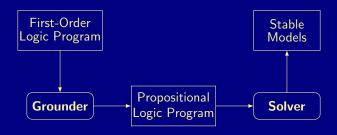
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Propositional Normal Logic Programs

 \blacksquare A logic program Π is a set of rules of the form

$$\underbrace{a}_{\mathsf{head}} \leftarrow \underbrace{b_1, \ldots, b_m, \sim c_1, \ldots, \sim c_n}_{\mathsf{body}}$$

- \blacksquare a and all b_i, c_i are atoms (propositional variables)
- lacksquare \leftarrow , $,,\sim$ denote if, and, and default negation
- intuitive reading: head must be true if body holds
- Semantics given by stable models, informally, sets X of atoms such that
 - \blacksquare X is a (classical) model of Π and
 - \blacksquare each atom in X is justified by some rule in Π



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$$\Pi = \left\{ a \leftarrow \sim b \quad b \leftarrow \sim a \quad x \leftarrow a, \sim c \quad x \leftarrow y \quad y \leftarrow x, b \right\}$$

$$CF(\Pi) = \left\{ a \leftarrow \neg b \quad b \leftarrow \neg a \quad x \leftarrow (a \land \neg c) \lor y \quad y \leftarrow x \land b \right\}$$

$$\cup \left\{ c \leftrightarrow \bot \right\}$$

$$LF(\Pi) = \left\{ (x \lor y) \rightarrow a \land \neg c \right\}$$
Classical models of $CF(\Pi)$:

$$\{b\}, \{b,c\}, \{b,x,y\}, \{b,c,x,y\}, \{a,c\}, \{a,b,c\}, \{a,x\}, \{a,c,x\}$$

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- Unsupported atoms
- Unfounded atoms



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Classical models of $CF(\Pi) \cup LF(\Pi)$:

- Unsupported atoms
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$$\Pi = \{ a \leftarrow \sim b \quad b \leftarrow \sim a \quad x \leftarrow a, \sim c \quad x \leftarrow y \quad y \leftarrow x, b \}$$

$$CF(\Pi) = \{ a \leftrightarrow (\bigvee_{(a \leftarrow B) \in \Pi} BF(B)) \mid a \in atom(\Pi) \}$$

$$BF(B) = \bigwedge_{b \in B \cap atom(\Pi)} b \land \bigwedge_{\sim c \in B} \neg c$$

$$LF(\Pi) = \{ (\bigvee_{a \in L} a) \rightarrow (\bigvee_{a \in L, (a \leftarrow B) \in \Pi, B \cap L = \emptyset} BF(B)) \mid L \in loop(\Pi) \}$$
Classical models of $CF(\Pi) \sqcup LF(\Pi)$:

Theorem (Lin and Zhao)

Let Π be a normal logic program and $X \subseteq atom(\Pi)$. Then, X is a stable model of Π iff $X \models CF(\Pi) \cup LF(\Pi)$.

- Size of $CF(\Pi)$ is linear in the size of Π
- Size of $LF(\Pi)$ may be exponential in the size of Π



```
(#Potassco
```

```
a :- not b. b :- not
$ clingo 0 prg.lp

clingo version 4.5.0
Reading from prg.lp
Solving...
Answer: 1
a x
```

\$ cat prg.lp

Models :

CPU Time : 0.000s

```
\underline{a} := \underline{not} \ \underline{b} := \underline{not} \ \underline{a}. \underline{x} := \underline{a}, \underline{not} \ \underline{c}. \underline{x} := \underline{y}. \underline{y} := \underline{x}, \underline{b}.
```

\$ cat prg.lp

```
(Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
Potassco
```

```
$ cat prg.lp
a := not b. b := not a. x := a, not c. x := y. y := x, b.
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```

```
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clingo version 4.5.0
Reading from prg.lp
Solving...
Answer: 1
a x
Answer: 2
b
SATISFIABLE
```

```
Models : 2
Calls : 1
```

<u>Time</u> : 0.000s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)

CPU Time : 0.000s

The reduct ϕ^X of a formula ϕ relative to a set X of atoms is defined as follows

$$\begin{array}{ll} \phi^{A} = \bot & \text{if } X \not\models \phi \\ \phi^{X} = \phi & \text{if } \phi \in X \\ \phi^{X} = (\psi^{X} \circ \mu^{X}) & \text{if } X \models \phi \text{ and } \phi = (\psi \circ \mu) \text{ for } \circ \in \{\land, \lor, \rightarrow\} \\ \phi^{X} = \top & \text{if } X \not\models \psi \text{ and } \phi = \sim \psi \end{array}$$

Let Φ be a formula and $X\subseteq \mathit{atom}(\Phi)$. Then, X is a stable model of Φ if X is a \subseteq -minimal model of Φ^X

a and $\sim \sim a$ are not the same



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Definition (Gelfond and Lifschitz et al.

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Some language constructs

Variables

$$p(X) := q(X)$$
 over constants $\{a,b,c\}$ stands for $p(a) := q(a), p(b) := q(b), p(c) := q(c)$

Conditional Literals

Disjunction

$$\blacksquare$$
 p(X); q(X):-r(X)

- Integrity Constraints
 - \blacksquare :- q(X), p(X)
- Choice

Aggregates

■
$$s(Y) := r(Y), 2 \#sum \{ X : p(X,Y), q(Y) \} 7$$



Basic methodology

Methodology

Generate and Test (or: Guess and Check)

Generator Generate potential stable model candidates (typically through non-deterministic constructs)

Tester Eliminate invalid candidates (typically through integrity constraints)

Peanutshell

Logic program = Data + Generator + Tester (+ Optimizer)



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Satisfiability testing

 $(a \leftrightarrow b) \land c$



Satisfiability testing

 $(a \leftrightarrow b) \land c$

```
{ a ; b ; c }.

:- not a, b.
:- a, not b.
:- not c.
```



Maximum satisfiability testing

"
$$(a \leftrightarrow b)$$
" + $(a \leftrightarrow b) \land c$

```
{ a ; b ; c }.
:- not a, b.
:- a, not b.
:- not c.
:~ a, b. [42@1]
:~ not a, not b. [69@2]
```



n-queensBasic encoding

```
{ queen(1..n,1..n) }.

:- { queen(I,J) } != n.
:- queen(I,J), queen(I,JJ), J != JJ.
:- queen(I,J), queen(II,J), I != II.
:- queen(I,J), queen(II,JJ), (I,J) != (II,JJ), I-J = II-JJ.
:- queen(I,J), queen(II,JJ), (I,J) != (II,JJ), I+J = II+JJ.
```



n-queens Advanced encoding

```
{ queen(I,1..n) } = 1 :- I = 1..n.
{ queen(1..n,J) } = 1 :- J = 1..n.
:- { queen(D-J,J) } >= 2, D = 2..2*n.
:- { queen(D+J,J) } >= 2, D = 1-n..n-1.
```



n-queens

(Experimental) constraint encoding

```
1 $<= $queen(1..n) $<= n.
#disjoint { X : $queen(X) $+ 0 : X=1..n }.
#disjoint { X : $queen(X) $+ X : X=1..n }.
#disjoint { X : $queen(X) $- X : X=1..n }.</pre>
```



Traveling salesperson Basic encoding (no instance)

```
1 { cycle(X,Y) : edge(X,Y) } 1 :- node(X).
1 { cycle(X,Y) : edge(X,Y) } 1 :- node(Y).

reached(X) :- X = #min { Y : node(Y) }.

reached(Y) :- cycle(X,Y), reached(X).

:- node(Y), not reached(Y).

#minimize { C,X,Y : cycle(X,Y), cost(X,Y,C) }.
```

Company Controls



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- Idea View inferences as unit propagation on nogoods
- Background
 - A nogood expresses an inadmissible assignment

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For example, given a rule a \leftarrow b \{Fa, Tb\} is a nogood (stands for \{a \mapsto F, b \mapsto T\})

Unit propagation on \{Fa, Tb\} infers

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CF(\Pi) = \left\{ a \leftrightarrow \neg b \quad b \leftrightarrow \neg a \quad c \leftrightarrow \bot \quad x \leftrightarrow (a \land \neg c) \lor y \quad y \leftrightarrow x \land b \right\} \\
\cup \left\{ B_1 \leftrightarrow \neg b \quad B_2 \leftrightarrow \neg a \quad B_3 \leftrightarrow a \land \neg c \quad B_4 \leftrightarrow y \quad B_5 \leftrightarrow x \land b \right\} \\
LF(\Pi) = \left\{ (x \lor y) \rightarrow a \land \neg c \right\}$$

Nogoods for $CF(\Pi)$ and $LF(\Pi)$

$$\Delta_{\Pi} = \{ \dots, \{ Fx, TB_3 \}, \{ Fx, TB_4 \} \dots \}$$

$$\cup \{ \dots, \{ Tx, FB_3, FB_4 \}, \dots \}$$

$$\cup \{ \dots, \{ FB_3, Ta, Fc \}, \dots \}$$

$$\cup \{ \dots, \{ TB_3, Fa \}, \{ TB_3, Tc \}, \dots \}$$

Size of Δ_{Π} is linear in the size of Π

Size of Λ_{Π} is (in general) exponential in the size of Π

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$$\Lambda_{\Pi} = \{ \{ Tx, FB_3 \}, \{ Ty, FB_3 \} \}$$

- Size of Λπ is linear in the size of Γ
 - $_{ t m}$ Size of Λ_{Π} is (in general) exponential in the size of Π
 - Satisfaction of Λ_{\square} can be tested in linear tir

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LF(\Pi) = \left\{ (x \lor y) \rightarrow B_3 \right\}$$

$$\Delta_{\Pi} = \{ \dots, \{ Fx, TB_3 \}, \{ Fx, TB_4 \} \dots \}$$

$$\cup \{ \dots, \{ Tx, FB_3, FB_4 \}, \dots \}$$

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$$\cup \{ \dots, \{ TB_3, Fa \}, \{ TB_3, Tc \}, \dots \}$$

$$\Lambda_{\Pi} = \{ \{ \mathbf{T}x, \mathbf{F}B_3 \}, \{ \mathbf{T}y, \mathbf{F}B_3 \} \}$$

- lacksquare Size of Δ_Π is linear in the size of Π
- $_{ t lue{}}$ Size of Λ_{Π} is (in general) exponential in the size of Π
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$$A_{\parallel} = \{\{1, 1, 1, 2, 3\}, \{1, 3, 1, 2, 3\}\}$$

- Size of Δ_{Π} is linear in the size of Π
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- \blacksquare Size of Δ_{Π} is linear in the size of Π
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 - Satisfaction of Λ_{\square} can be tested in linear time

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Stable Models as Solutions

Theorem

Let Π be a normal logic program and $X \subseteq atom(\Pi)$. Then, X is a stable model of Π iff $X = \mathbf{A}^T \cap atom(\Pi)$ for a (unique) solution **A** for $\Delta_{\Pi} \cup \Lambda_{\Pi}$.

- All inferences can be seen as unit propagation on nogoods
- Nogoods readily available as conflict reasons



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Advantages

- Stable model computation as Boolean constraint solving.
- All inferences can be seen as unit propagation on nogoods
- Nogoods readily available as conflict reasons



Conflict-Driven Constraint Learning (CDCL)

```
loop
                                     // assign deterministic consequences
    propagate
    if no conflict then
        if all variables assigned then return variable assignment
        else decide
                             // non-deterministically assign some variable
    else
        if top-level conflict then return unsatisfiable
        else
            analyze
                            // analyze conflict and add conflict constraint
            backjump // undo assignments violating conflict constraint
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The solver clasp

- Beyond deciding (stable) model existence, clasp allows for
 - Enumeration
 - Projective enumeration
 - Intersection and Union
 - Multi-objective Optimization
 - and combinations thereof
- clasp allows for
 - ASP solving (smodels format)
 - MaxSAT and SAT solving (extended dimacs format)
 - PB solving (opb and wbo format)
- clasp pursues a coarse-grained, task-parallel approach to parallel search via shared memory multi-threading

(without solution recording) (without solution recording) (linear solving process)

The solver clasp

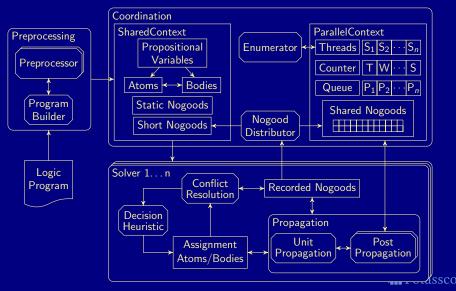
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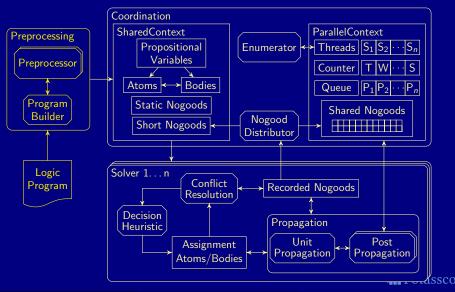
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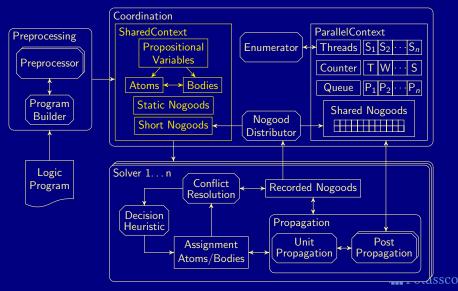
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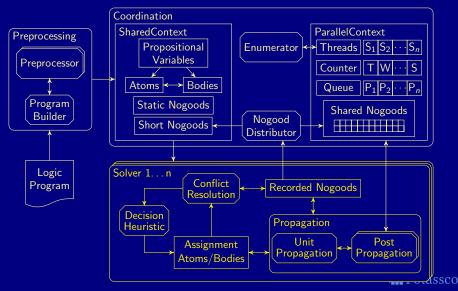
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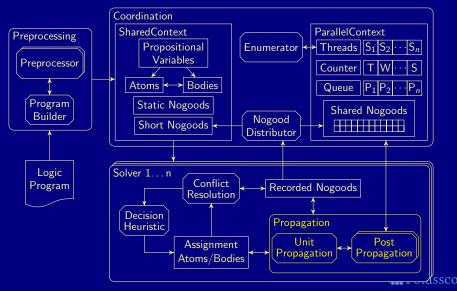
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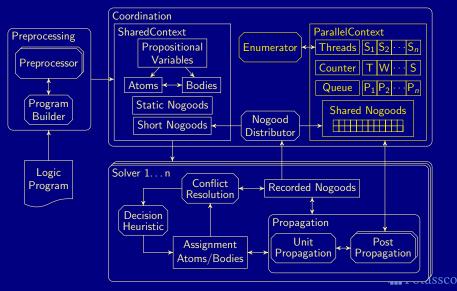






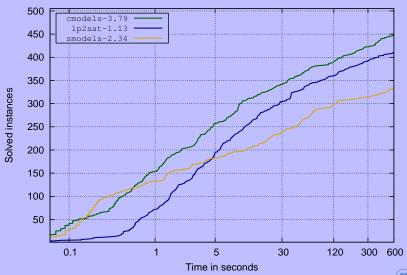


Multi-threaded architecture of clasp

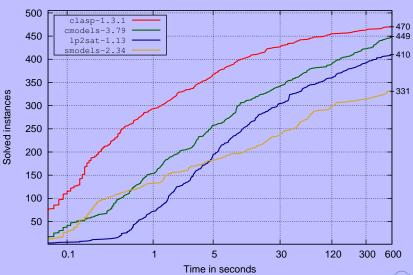


NP-Track Second ASP Competition

Run on: Dual-Processor Intel Xeon Quad-Core E5520

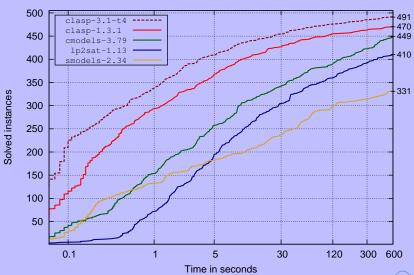


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Outline

- 1 Introduction
- 2 Foundations
- 3 Modeling
- 4 Algorithms and Systems
- 5 Potassco
- 6 Summary



Potassco, the Potsdam Answer Set Solving Collection, bundles tools for ASP developed at the University of Potsdam:

- Grounder gringo, lingo
- Solver clasp, claspfolio, claspar, aspeed
- Grounder+Solver Clingo, Clingcon, ROSoClingo
- Further Tools aspartame, aspcud, asprin, chasp, claspre, clavis, coala, fimo, insight, metasp, plasp, piclasp, etc

asparagus.cs.uni-potsdam.de



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- ASP offers efficient and versatile off-the-shelf solving technology
- ASP offers an expanding functionality and ease of use
 - rapid application development tool
- ASP has a growing range of applications



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http://potassco.sourceforge.net

