



Resource allocation and utilization in the Blue Gene/L supercomputer

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Agenda

- Blue Gene/L Background
- Blue Gene/L Topology
- Resource Allocation
- Simulation Results

Blue Gene/L - Overview

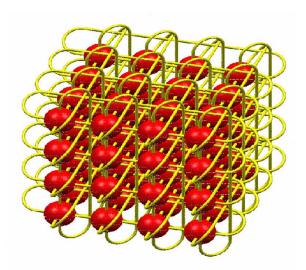
- First member of IBM Blue Gene family of supercomputers
- Machine configurations range from 1000 to 64,000 nodes
- The world fastest supercomputer
 - Rated first in the last top500 list (November 2004)
 - Machine size of 16K nodes
- Selected customers:
 - Lawrence Livermore National Laboratory
 - Japan's National Institute of Advanced Industrial Science and Technology
 - Lofar radio telescope run by Astron in the Netherlands
 - Argonne National Laboratory

Blue Gene/L Philosophy

- Designed for highly parallel applications
- Traditional Linux and MPI programming models
- Extendable and manageable
 - simple to build and operate
- Vastly improved price/performance
 - choosing simple low power building block
 - highest possible single threaded performance is not relevant, aggregate is!
- Floor space and power efficiency
- BlueGene/L = Cellular architecture + aggressive packaging + scalable software

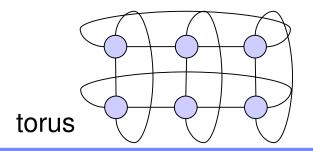
BlueGene/L cellular architecture

- The design of BlueGene/L is substantially different from the traditional supercomputers (NEC Earth Simulator, ASCI machines) that uses large clusters of SMP nodes
- Very large number (64K) of simple identical nodes
 - Low cost, low power, PPC microprocessors (700Mhz)
- ♦ Geometry: 64x32x32, based on 3D torus
 - Low latency, high bandwidth propriety interconnect
 - ♦ I/O physically separated from computations
 - At most one process per CPU at a time
- Scalable and extendable architecture
 - Computational power of the machine can be expanded by adding more "building blocks"



Jobs in Blue Gene/L

- Blue Gene/L runs parallel jobs
 - Set of task running together, communicating via message-passing
 - Each job has a set of attributes
 - ♦ Size # of threads (and thus nodes)
 - ♦ 3D Shape
 - ♦ Communication pattern torus or mesh





What is a Job Partition?

- A partition is
 - A set of nodes
 - A set of communication links
 - Which connect the nodes as a torus or a mesh
- Partitions are isolated
 - A single partition accommodates a single job
 - No sharing of nodes or links between partitions

Job Management for Blue Gene/L

- Users submit jobs to the Blue Gene/L scheduler
 - The scheduler maintains a queue of submitted jobs
- ♦ The scheduler's task:
 - Choose the next job to run from the queue
 - Allocate resources for the job
 - Launch the job
 - Monitor the job until termination
 - Signals, debugging...

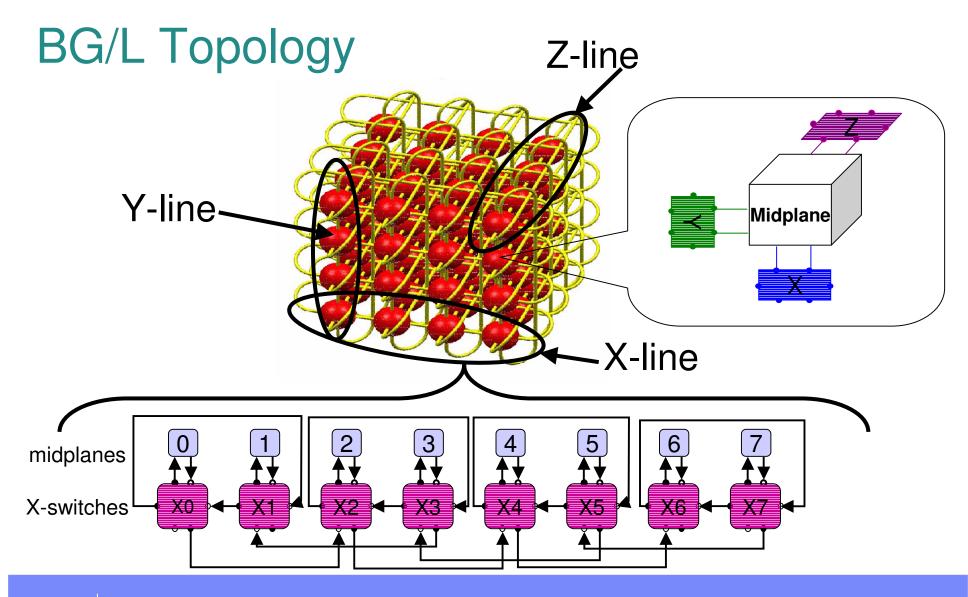


Job Management Challenges

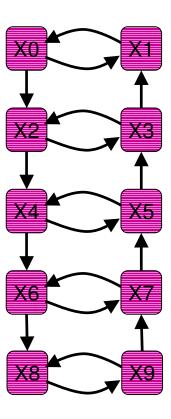
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 - Group nodes into midplanes
- How do we maximize machine utilization ?
 - Extend toroidal topology to <u>multi-toroidal topology</u>

Scalability via Midplanes

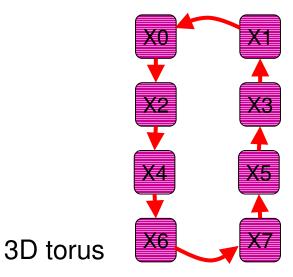
- Nodes are grouped into 512-node units called midplanes
 - ♦ A midplane is an 8x8x8 3D mesh
 - Each internal node is connected directly to at most six internal neighbors
 - Midplanes are connected to each other through switches
- Scalability achieved by sacrificing granularity of management
 - Midplane is the minimal allocation unit
 - Not all nodes may be utilized for a given job
 - ♦ In practice, we deal with a 128-node machine instead of 64K nodes
 - For all aspects of job management

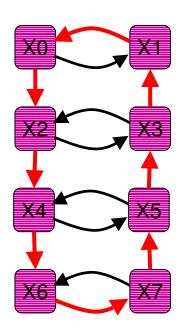


- Lines have "multi-toroidal topology"
 - Can be easily extended

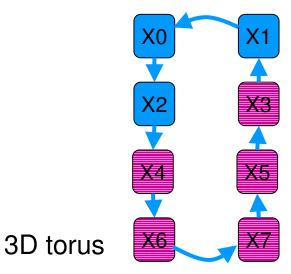


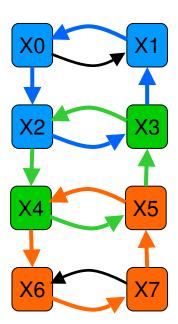
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 - Can be easily extended
 - Can be connected as a torus





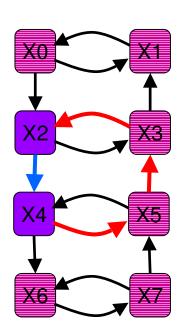
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 - Multiple toroidal partitions can coexist







- Lines have "multi-toroidal topology"
 - Can be easily extended
 - Can be connected as a torus
 - Multiple toroidal partitions can coexist
 - More than one way to wire a set of midplanes



Resource Allocation

- Challenges
 - High machine utilization
 - Short response time (of jobs)
 - On-line problem
- Requirements
 - Satisfy job requests for size, shape, and connectivity (torus or mesh)
 - Deal with faulty resources (nodes and wires)
- Two kinds of dedicated resources to manage
 - Node allocation
 - Link allocation

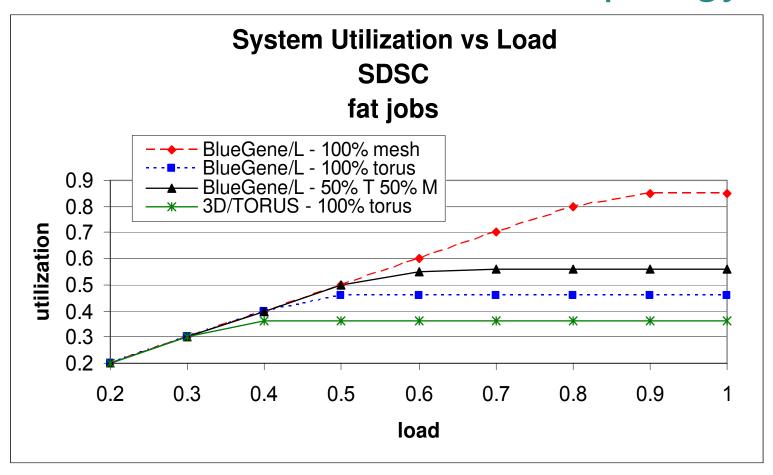
Allocation Algorithm

- Finding a partition: scan the 3D machine
 - Find all free partitions that match the shape/size of a job
 - For each candidate partition, find <u>if and how</u> it can be wired
 - From all wireable partitions, choose the "best" partition
 - use flexible criteria e.g. minimal number of links
- Wiring a partition
 - Static wire lookup tables per dimension
 - Availability of wires (previous allocation or faults) is checked
 - Find suitable links in (almost) constant time
 - Small memory footprint despite the huge number of links

Simulated Environment

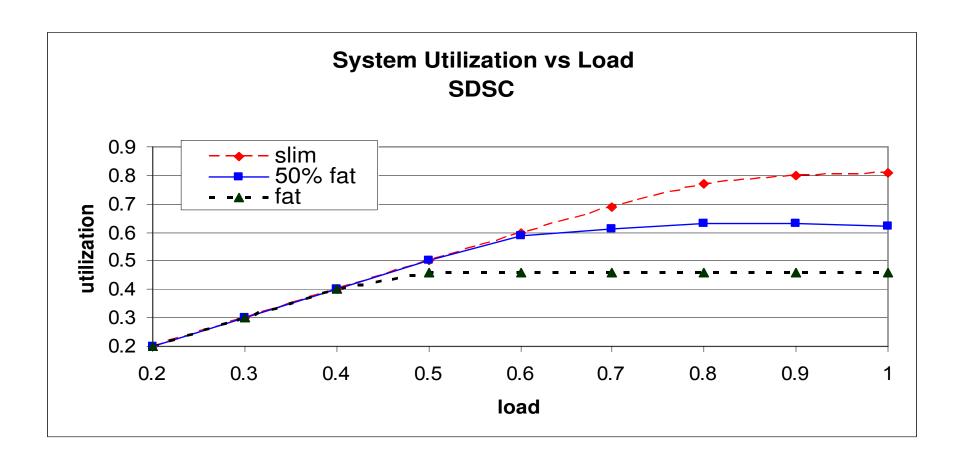
- Faithful simulation of Blue Gene/L
 - 128 midplanes
- Scheduler invoked when a job arrives or terminates
- Scheduling policy
 - Aggressive backfilling
 - If the job at the head of the queue cannot be accommodated we try to allocate another job out of order
- Workloads (benchmarks)
 - Arrival times, runtimes, size, shape, torus/mesh
 - Based on real parallel systems' logs
 - This presentation: San Diego Supercomputer Center (SDSC)

The benefits of multi-toroidal topology





The influence of job shapes on utilization



Summary

- Solution
 Solution
 Serious
 State of Supercomputer
 Scalability and many new challenges
- Scalability of system management is achieved by sacrificing granularity
 - Represent the machine as a smaller system consisting of collections of nodes
- Blue Gene/L's novel network topology has considerable advantages compared to traditional interconnects (such as 3D tori)
- The challenges are successfully met with a combined hardware and software solution



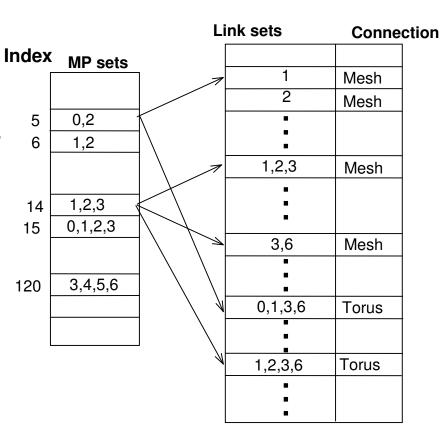
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Link Allocation

- The problem:
 - Siven a partition, fined links in all the lines that participate in the partition for all three dimensions to wire a partition attempting to best utilize future allocations.
- Solution main idea:
 - Suild a lookup table with the partitions wiring possibilities
 - ♦ The dimension are independent → Table per dimension
 - ♦ All lines in a dimension are equal → Table contain information on one line
 - ◆ There are not so many whys to wire a partition → consume relatively small amount of memory

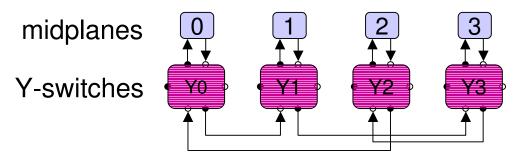
The Lookup table

- A table per topology dimension
 - The index is a possible set Index of midplanes
 - Each entry contains all sets of links that can wire it as a torus or as a mesh
- Built once at startup time
- Siven a partition, use tables to find link set in each dimension
- Eliminate non-available sets, output "best" among available

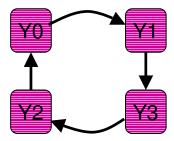


Y & Z lines Connectivity

No "multi-toroidal topology"



Or can be drown that way (without the midplanes):



Can accommodate only one torus partition at a time