



Compiler Mediated Performance of a Cell Processor

Alexandre Eichenberger, Kathryn O'Brien, Kevin O'Brien, Peng Wu, Tong Chen, Peter Oden, Daniel Prener, Janice Shepherd, Byoungro So, Zehra Sura, Amy Wang, Tao Zhang, Peng Zhao, Yaoqing Gao

www.research.ibm.com/cellcompiler/compiler.htm

Haifa Compiler and Architecture Seminar - 2005

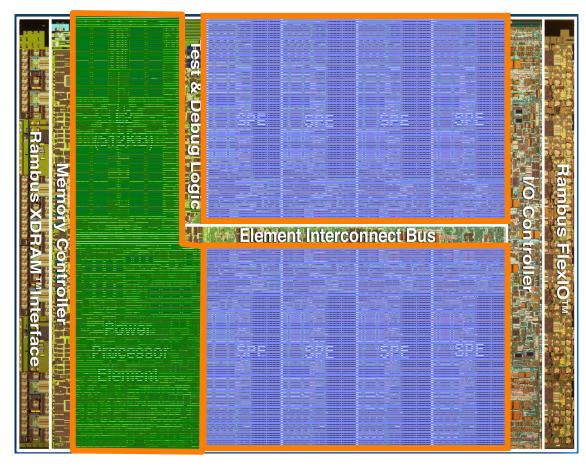


Background

- □ Prototype compiler
 - ➤ Some functionality shipped in Alphaworks Cell xlc compiler
- Based on and integrated with the product code base
- Collaboration with compiler development group
- Many research issues still in progress



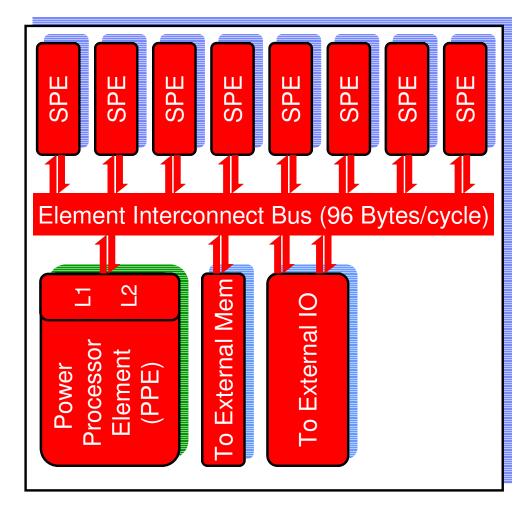
Cell Broadband Engine



- Multiprocessor on a chip
 - ➤ 241M transistors, 235mm²
 - > 200 GFlops (SP) @3.2GHz
 - 200 GB/s bus (internal) @ 3.2GHz
- **☐** Power Proc. Element (PPE)
 - > general purpose
 - > running full-fledged OSs
- □ Synergistic Proc. Element (SPE)
 - optimized for compute density



Cell Broadband Engine Overview



- ☐ Heterogeneous, multi-core engine
 - ➤ 1 multi-threaded power processor
 - up to 8 compute-intensive-ISA engines
- Local Memories
 - fast access to 256KB local memories
 - globally coherent DMA to transfer data
- □ Pervasive SIMD
 - > PPE has VMX
 - > SPEs are SIMD-only engines
- ☐ High bandwidth
 - > fast internal bus (200GB/s)
 - → dual XDRTM controller (25.6GB/s)
 - two configurable interfaces (76.8GB/s)
 - numbers based on 3.2GHz clock rate

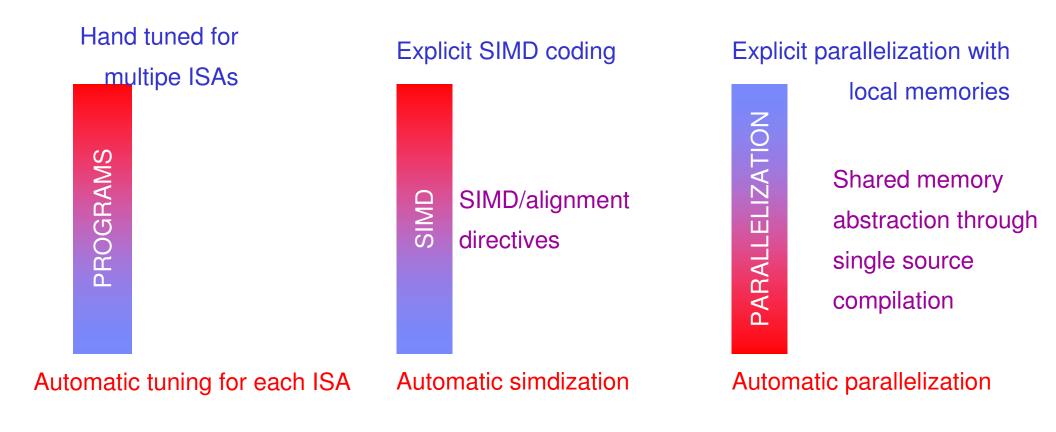
- 8 Bytes (per dir)
- 16Bytes (one dir)





Compiler support for the full spectrum of Cell programming expertise

Highest performance with programmer control



Highest Productivity with fully automatic compiler technology



Outline

Part 1: Automatic SPE tuning

Multiple-ISA hand-tuned programs

Automatic tuning for each ISA

Part 3: Automatic simdization

Explicit SIMD coding

SIMD/alignment directives

Automatic simdization

Part 2: Parallelization and memory abstraction

Explicit parallelization with

letetal eriaerietaiaa

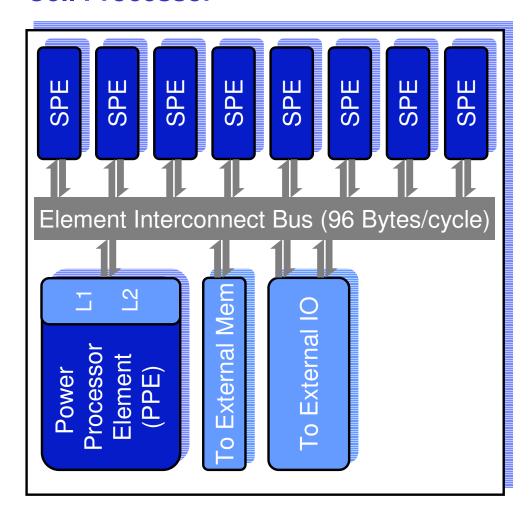
Shared memory, single program ahstrantinn

Automatic parallelization



Cell Architecture Overview

Cell Processor



- □ PPE executes traditional code
- **□** SPE optimized for
 - high compute throughput
 - small area footprint
- □ SPE tradeoff
 - lower hardware complexity
 - peak performance requires compiler assistance

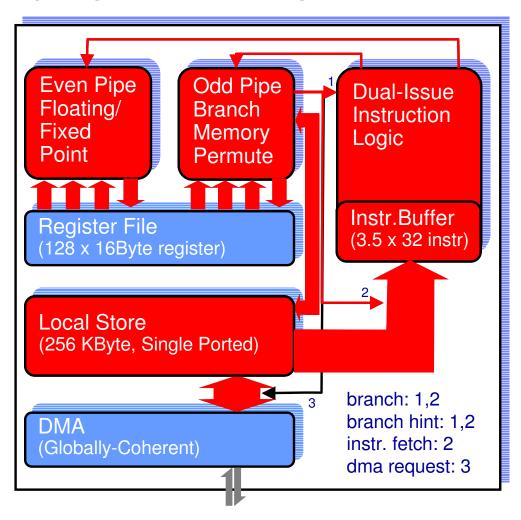
- 8 Bytes (per dir)
- 16Bytes (one dir)





Architecture: Relevant SPE Features

Synergistic Processing Element (SPE)



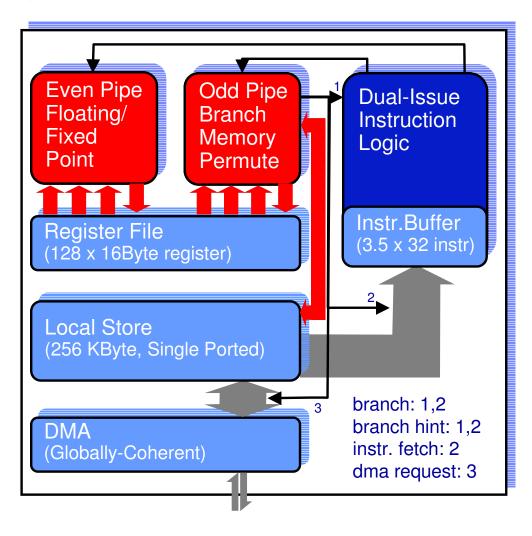
- 8 bytes (per dir)
- 16 bytes (one dir)
- 128 bytes (one dir)

- ☐ SIMD-only functional units
 - 16-bytes register/memory accesses
- **☐** Simplified branch architecture
 - no hardware branch predictor
 - compiler managed hint/predication
- Dual-issue for instructions
 - full dependence check in hardware
 - must be parallel & properly aligned
- □ Single-ported local memory
 - aligned accesses only
 - contentions alleviated by compiler



Feature #1: Functional Units are SIMD Only

SPE



- **☐** Functional units are SIMD only
 - ➤ all transfers are 16 Bytes wide,
 - including register file and memory
- How to handle scalar code?

8 bytes (per dir)



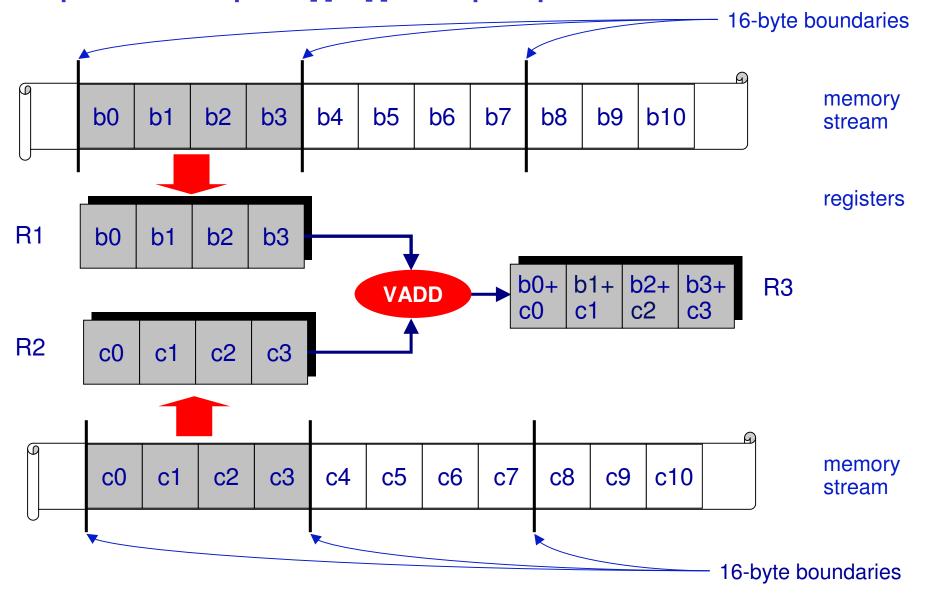


128 bytes (one dir)



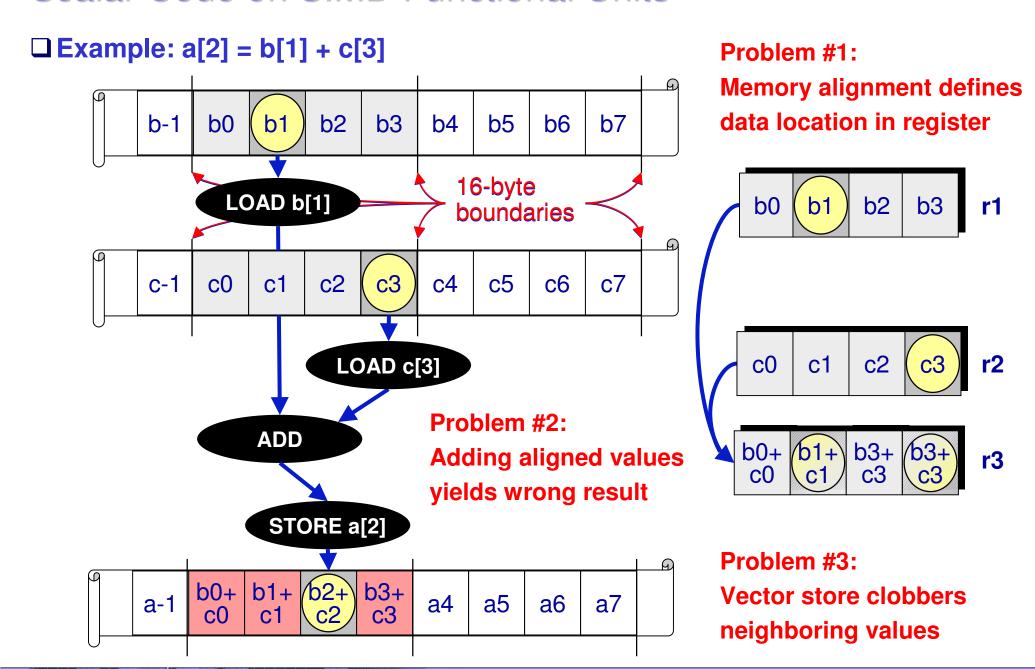
Single Instruction Multiple Data (SIMD)

Meant to process multiple "b[i]+c[i]" data per operation





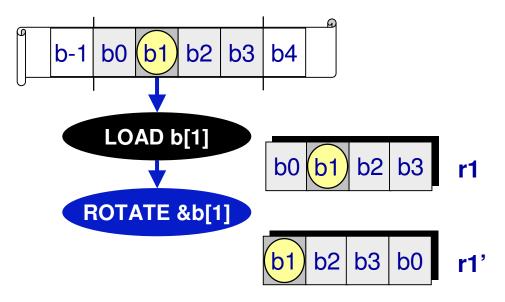
Scalar Code on SIMD Functional Units





Scalar Load Handling

☐ Use read-rotate sequence



□ Overhead (1 op, in blue)

one quad-word byte rotate

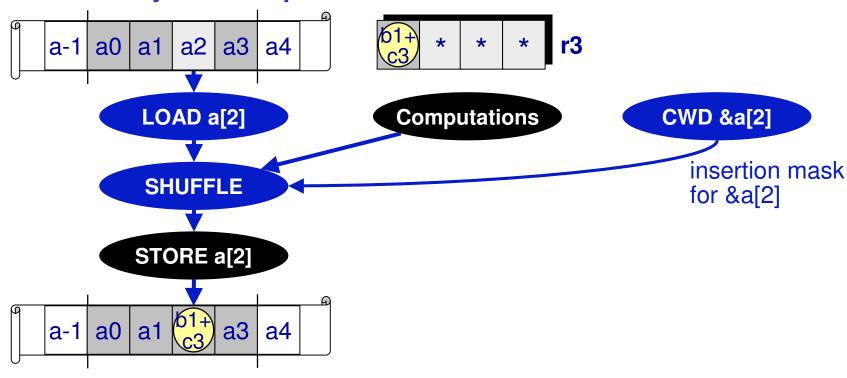
□ Outcome

- desired scalar value always in the first slot of the register
- this addresses Problems 1 & 2



Scalar Store Handling

☐ Use read-modify-write sequence



- ☐ Overhead (1 to 3 ops, in blue)
 - one shuffle byte, one mask formation (may reuse), one load (may reuse)
- **□** Outcome
 - ➤ SIMD store does not clobber memory (this addresses Problem 3)

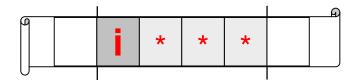


Optimizations for Scalar on SIMD

- ☐ Significant overhead for scalar load/store can be lowered
- ☐ For vectorizable code
 - generate SIMD code directly to fully utilize SIMD units
 - done by expert programmers or compilers (see SIMD presentation)

☐ For scalar variable

allocate scalar variables in first slot, by themselves

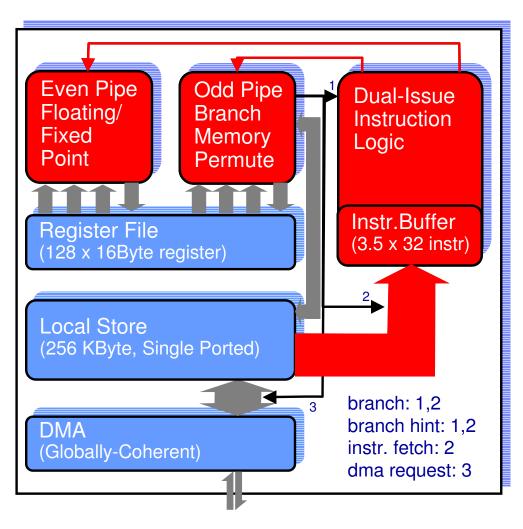


- eliminate need for rotate when loading
 - data is guaranteed to be in first slot (Problems 1 & 2)
- eliminate need for read-modify-write when storing
 - other data in 16-byte line is garbage (Problem 3)
- can also deal with the alignment of scalar data



Feature #2: Software-Assisted Instruction Issue

SPE



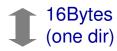
■ Dual-issue for Instructions

- can dual-issue parallel instructions
- > code layout constrains dual issuing
- full dependence check in hardware

□ Alleviate constraints by

making the scheduler aware of code layout issue

8 Bytes (per dir)







Alleviating Issue Restriction

☐ Scheduling finds the best possible schedule

dependence graph modified to account for latency of false dependences

☐ Bundling ensures code layout restrictions

- keep track of even/odd code layout at all times
- swap parallel ops when needed
- insert (even or odd) nops when needed

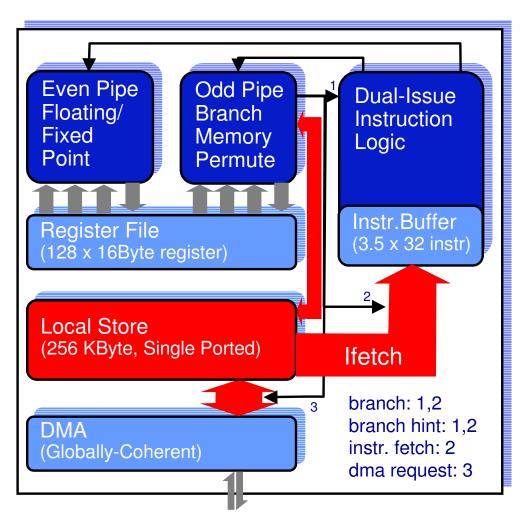
□ Engineering issues

- each function must start at known even/odd code layout boundary
- one cannot add any instructions after the last scheduling phase as it would impact the code layout and thus the dual-issuing constraints



Feature 3: Single-Ported Local Memory

SPE



- □ Local store is single ported
 - denser hardware
 - > asymmetric port
 - 16 bytes for load/store ops
 - 128 bytes for IFETCH/DMA
 - > static priority
 - DMA > MEM > IFETCH
- ☐ If we are not careful, we may starve for instructions

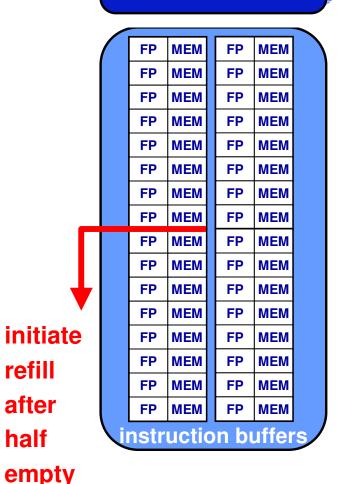
- 8 Bytes (per dir)
- 16Bytes (one dir)





Instruction Starvation Situation

Dual-Issue Instruction Logic



- There are 2 instruction buffers
 - up to 64 ops along the fall-through path
- First buffer is half-empty
 - can initiate refill
- When MEM port is continuously used
 - starvation occurs (no ops left in buffers)

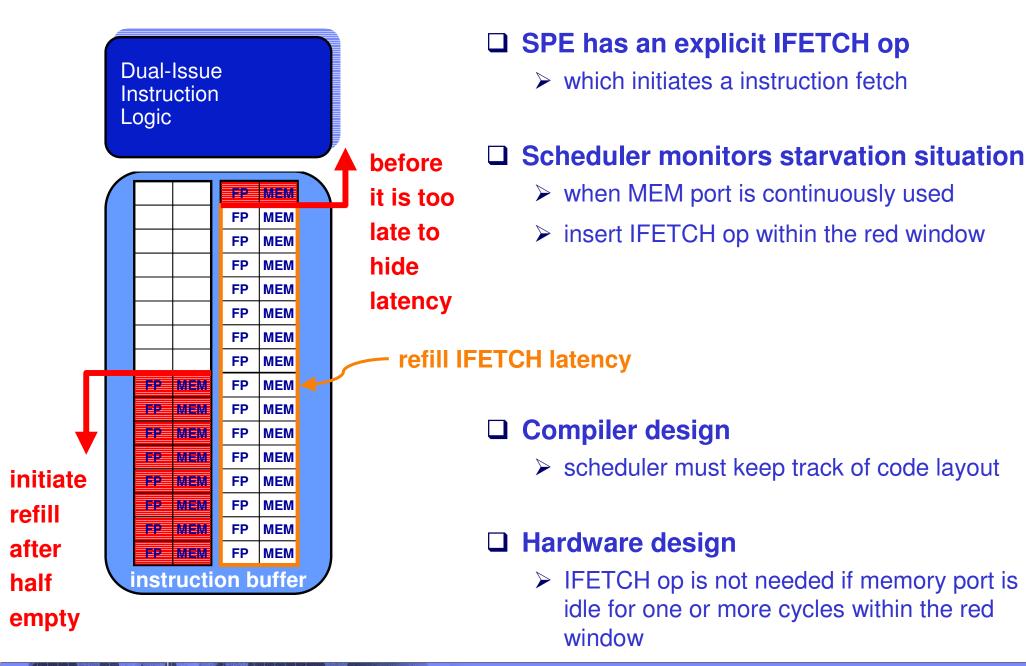
refill

after

half



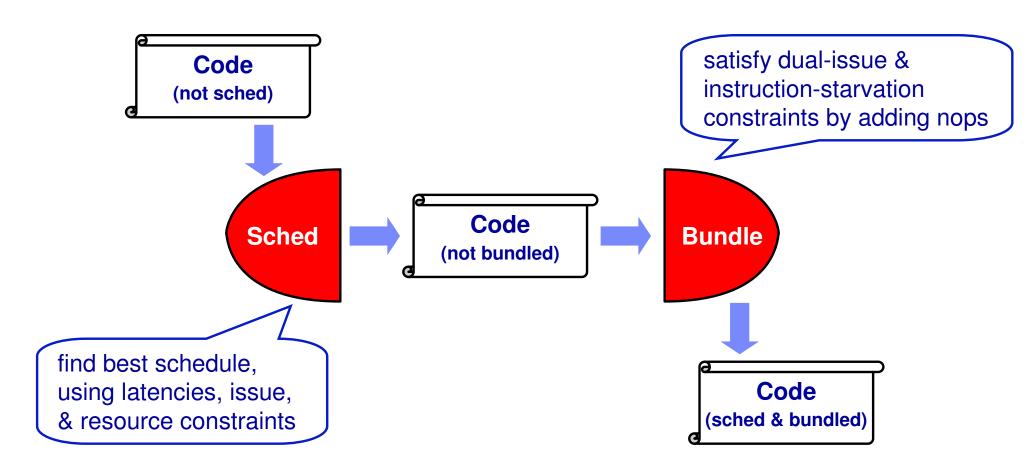
Instruction Starvation Prevention





Engineering Issues for Dual-Issue & Starvation Prevention

☐ Initially, the scheduling and bundling phases were separate



Problem: Bundler adds an IFETCH to prevent starvation.

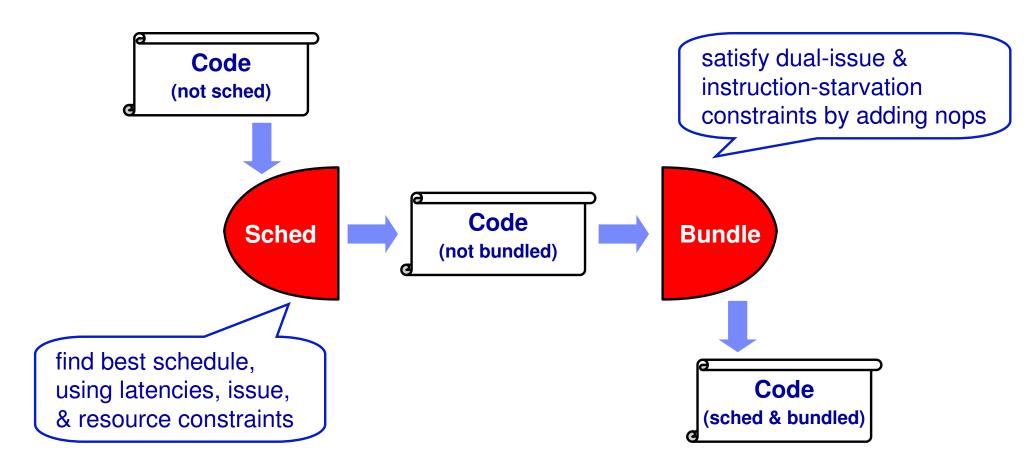
A better schedule could be found if the scheduler had known that.

But the schedule is already "finalized".



Engineering Issues for Dual-Issue & Starvation Prevention

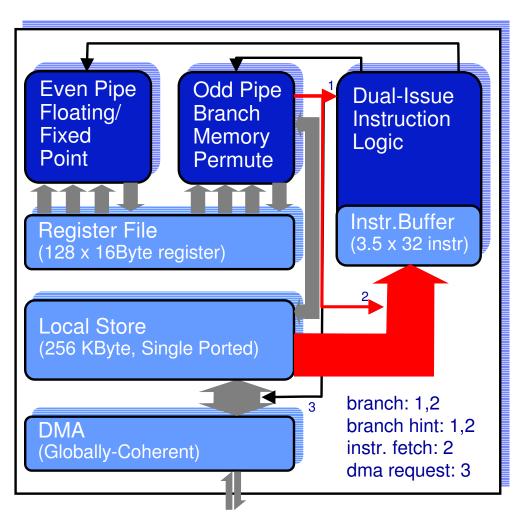
☐ We integrate Scheduling and Bundling tightly, on a cycle per cycle basis





Feature #4: Software-Assisted Branch Architecture

SPE



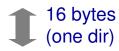
☐ Branch architecture

- no hardware branch-predictor, but
- compare/select ops for predication
- software-managed branch-hint
- > one hint active at a time

■ Lowering overhead by

- predicating small if-then-else
- hinting predictably taken branches

8 bytes (per dir)





128 bytes (one dir)



Hinting Branches & Instruction Starvation Prevention

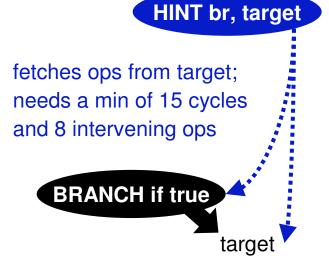
Dual-Issue Instruction Logic

- □ SPE provides a HINT operation
 - fetches the branch target into HINT buffer
 - no penalty for correctly predicted branches

WEW FP MEM FP MEM FP MEM FP MEM MEM FP FP **MEM** FP MEM МЕМ FP FP MEM FP MEM MEM MEM MEM MEM MEM **HINT** buffer nstruction buffers

IFETCH window

refill latency

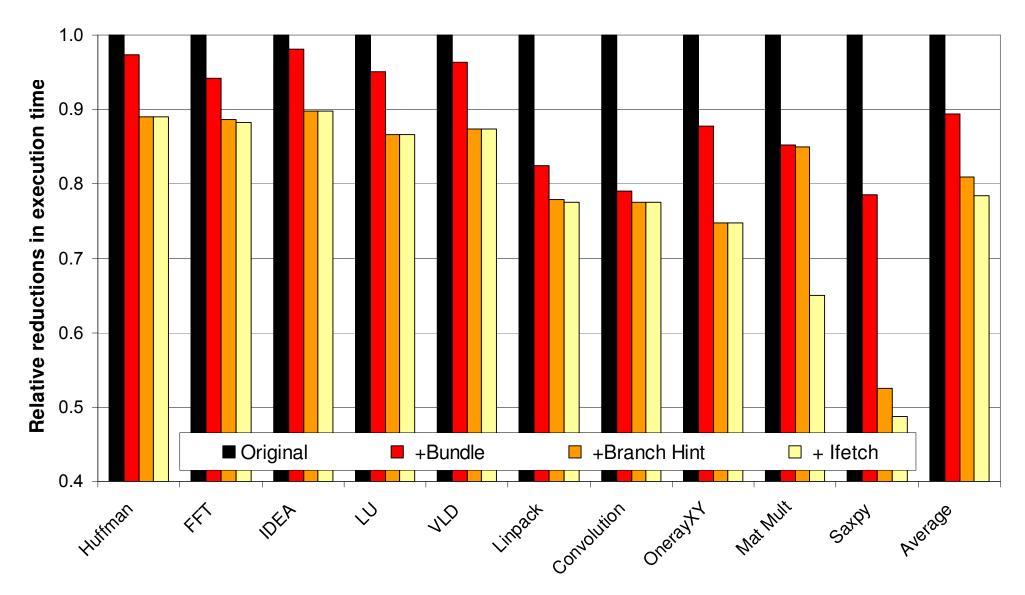


compiler inserts hints when beneficial

- ☐ Impact on instruction starvation
 - after a correctly hinted branch, IFETCH window is smaller



SPE Optimization Results



single SPE performance, optimized, simdized code

 $(avg 1.00 \rightarrow 0.78)$



Outline

Multiple-ISA hand-tuned

programs

Automatic tuning for each ISA

Part 3: Automatic simdization

Explicit SIMD coding

SIMD/alignment directives

Automatic simulzation

Part 2: Parallelization and memory abstraction

Explicit parallelization with

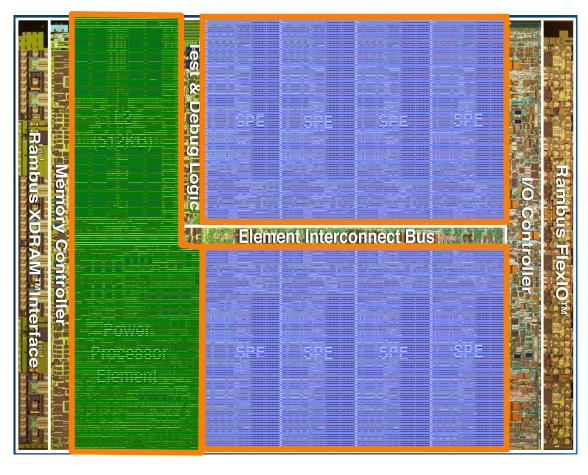
letetal eriperiera

Shared memory, single program ahsiradion.

Automatic parallelization



Cell Broadband Engine



- Multiprocessor on a chip
 - ➤ Power Proc. Element (PPE)
 - general purpose
 - running full-fledged OSs
 - > Synergistic Proc. Element (SPE)
 - optimized for compute density
- □ Compiler support for parallelizing across the heterogeneous processing elements



Single Source Compiler

- ☐ user prepares an application as a collection of one or more source files containing user directives targetting the Cell architecture
- □ compiler, guided by these directives, takes care of the code partitioning between PE and SPE
- **□** compiler takes care of data transfers.
 - ➤ identifies accesses in SPE functions that refer to data in system memory locations
 - uses software cache or static buffers to manage transfer of this data to/from SPE local stores
- □ compiler takes care of code size
 - > explore extending Code partitioning to Single Source, i.e. automatic partitioning based on functionality rather than size



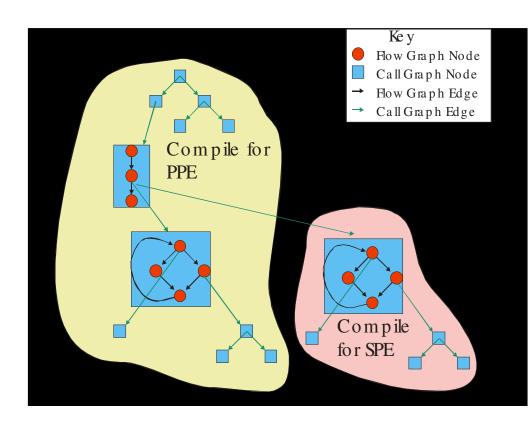
Using OpenMP to partition/parallelize across Cell

- □ Single source program contains C or Fortran with user directives or pragmas
- ☐ Compiler 'outlines' all code within the pragmas into separate functions compiled for the SPE.
- □ Replaces 'outlined' code with call to the parallel runtime and compiles this code for the PPE
- Master thread continues to execute on PPE and participate in workshare constructs
- □ PPE Runtime
 - places outlined functions on a work queue containing information about number of iterations to execute, or 'chunk' size for each SPE
 - Creates up to 8 SPE threads to pull work items (outlined parallel functions) from queue and execute on SPEs
- May wait for SPE completion, or proceed with other PPE statement execution



Cloning for heterogeneous processors

- □ Outlined function becomes new node in call graph
- □ In pass 2 of TPO, using whole program call graph, outlined function is cloned, then specialized to create a ppe and an spe version
- □ All called functions must also be cloned
- □ SPE call sites modified to call SPE versions of cloned subroutines
- □ Partitioning pass creates SPE and PPE partitions and invokes lower level optimizer for machine specific optimization





"Single Source" Compiler, using OpenMP

```
Foo1();

#pragma Omp parallel for

for( i =0; i<10000; i++)

A[i] = x* B[i];

Foo2();
```

outline omp

void ol\$1() for(i =0; i<10000; i++) $A[i] = x^* B[i];$

clone for SPE

Compile for PPE

```
Foo1();
Call omp-rte-init;
Call omp_rte_do_par;
Foo2();
```

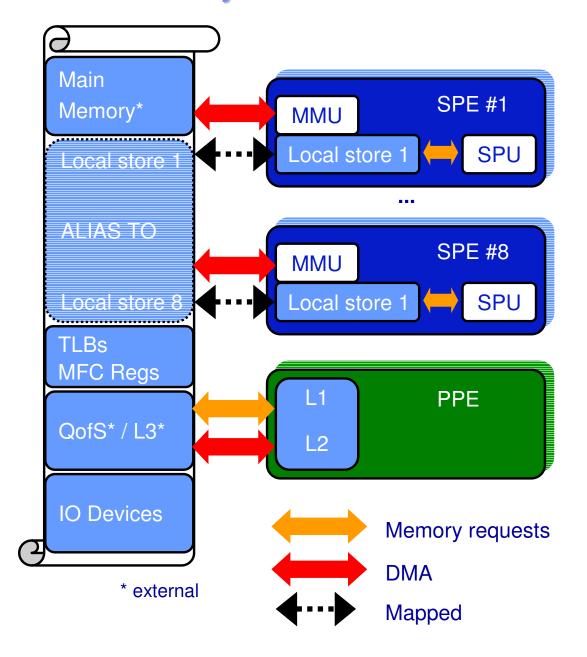
clone for PPE

```
void OL$1_PPE()
for( i=LB; i<UB; i++) ´
A[i] = x * B[i];</pre>
```

void OL\$1_SPE()
for(k=LB; k<UB; k++)
 DMA 100 B elements into B´
for (j=0; j<100; j++)
 A´[j] = cache_lookup(x) * B´[j];
 DMA 100 A elements out of A´</pre>



Cell Memory & DMA Architecture



- □ Local stores are mapped in global address space
- □ PPE
 - > can access/DMA memory
 - > set access rights
- □ SPE can initiate DMAs
 - > to any global addresses,
 - including local stores of others.
 - > translation done by MMU

- □ Note
 - all elements may be masters, there are no designated slaves

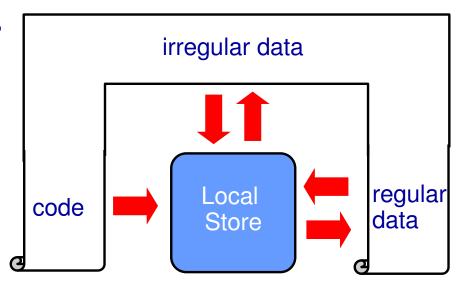


Competing for the SPE Local Store

Local store is fast, need support when full.

Provided compiler support:

- ☐ SPE code too large
 - > compiler partitions code
 - partition manager pulls in code as needed



- □ Data with regular accesses is too large
 - > compiler stages data in & out
 - using static buffering
 - can hide latencies by using double buffering
- □ Data with irregular accesses is present
 - > e.g. indirection, runtime pointers...
 - use a software cache approach to pull the data in & out (last resort solution)



How can we run programs that have lots of data?

- Data won't all fit in Local Store
 - ➤ Solution: Use System Memory, its large and virtual
 - But the SPU doesn't have Load/Store access to it
 - ➤ The compiler can automatically manage the transferring of Data between System Memory, and Local Store
 - ➤ We call this Data Partitioning



Data Partitioning

- □ Single Source assumption: all data lives in System Memory
- Naïve implementation, every load and store requires a dma operation
 - ➤ Too costly (~300 cycles per load or store)
 - ➤ MP will require locking on every reference
- **□What can be done to make this acceptable?**



Reducing the Overhead of Accesses to System Memory

- □ Rather than executing a DMA transaction for every variable access, we would like to bring data over in larger pieces, and keep it in Local Store for some portion of its lifetime
- There are several techniques that can accomplish this
 - > Prefetching predictable references, and accumulating writes
 - > Software Cache
 - on demand, but leverage spatial and temporal locality
 - requires additional instructions inline, so it is essentially a fallback strategy
 - ➤ We can apply Tiling to increase reuse for both of these



Software Cache for Irregular Accesses

■ Data with irregular accesses

- cannot reside permanently in the SPE's local memory (typically)
- thus reside in global memory
- when accessed,
 - must translate the global address into a local store address
 - must pull the data in/out when its not already present

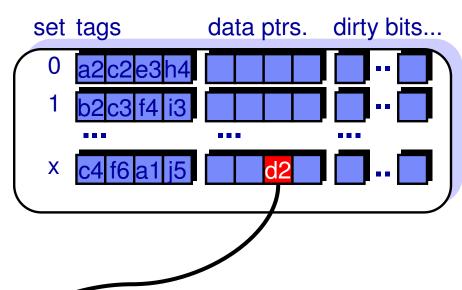
☐ Use a software cache

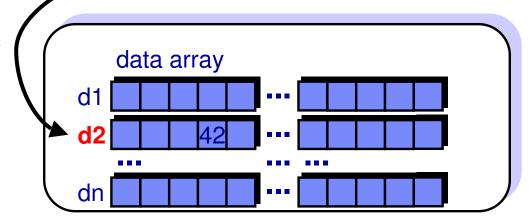
- managed by the SPEs in the local store
- generate DMA requests to transfer data to/from global memory
- use 4-way set associative cache to naturally use the SIMD units of the SPE



Software Cache Overview

- □ A portion of Local Store is set aside to hold the cache
- □Cache is made up of two arrays
 - ➤ Tag Array: Contains the comparands for the address lookups and pointers to the data lines, also contains "dirty-bits" for MP support
 - ➤ Data Array: Contains the data lines
- **□Geometry**
 - Currently, 4-way Set Associative
 - ➤ line size is 128 bytes, and there are 128 of them in each set
 - > these parameters can be changed
- □Total size, Tags (16K) + Data(64K) is 80K





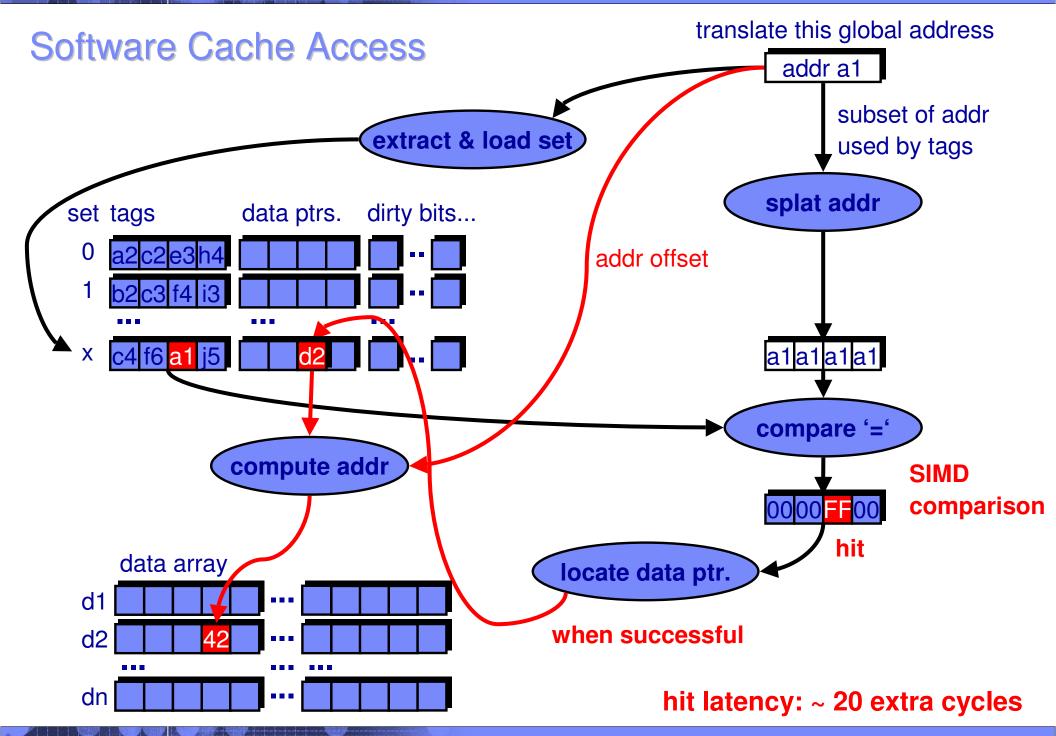


Software Cache Lookup

- □ The cache lookup code is inserted inline at each Read or Write reference to a Cacheable Variable
- ☐ This code is optimized along with all the other instructions
- □ The branch to the misshandler is treated as a regular instruction throughout optimization, and expanded only at the very end of compilation
- □ The misshandler uses a tailored register convention, so that it has no impact on the hit path

20:	VAND	vr844=gr664,vr842
20:	LI	vr847=0x10203
20:	VLR	*vr846=vr847
20:	VSHUFB	vr848=gr664,gr664,vr846
20:	VLR	*vr845=vr848
20:	VAND	vr849=vr843,vr845
20:	VLQ	vr850=.L_tagaddr(relative,0)
20:	A	gr851=vr844,vr850
20:	VLQ	vr852=.L_tagarray(gr851,0)
20:	VLQ	vr853=.L_tagarray(gr851,16)
20:	VANDC	vr854=gr664,vr843
20:	VCEQW	vr855=vr849,vr852
20:	VGBB	vr856=vr855
20:	VCNTLZ	vr857=vr856
20:	VQBR	vr858=vr853,vr857,gr1
20:	MISS	*vr858,.L_tagarray=gr664,vr856,vr858
20:	A	gr859=vr854,vr858
20:	VLR	*gr799=gr859
20:	LI	vr847=0x10203
20:	VLR	*vr846=vr847
20:	VSHUFB	vr848=gr664,gr664,vr846
20:	VLR	*vr845=vr848
20:	VLQ	vr800=c[]0(gr799,0)
20:	LR	*vr663=vr800

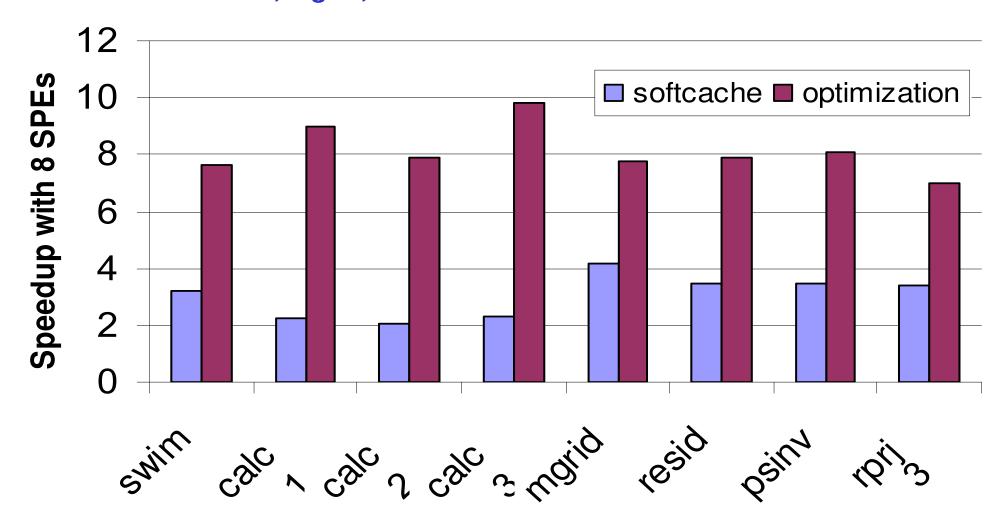






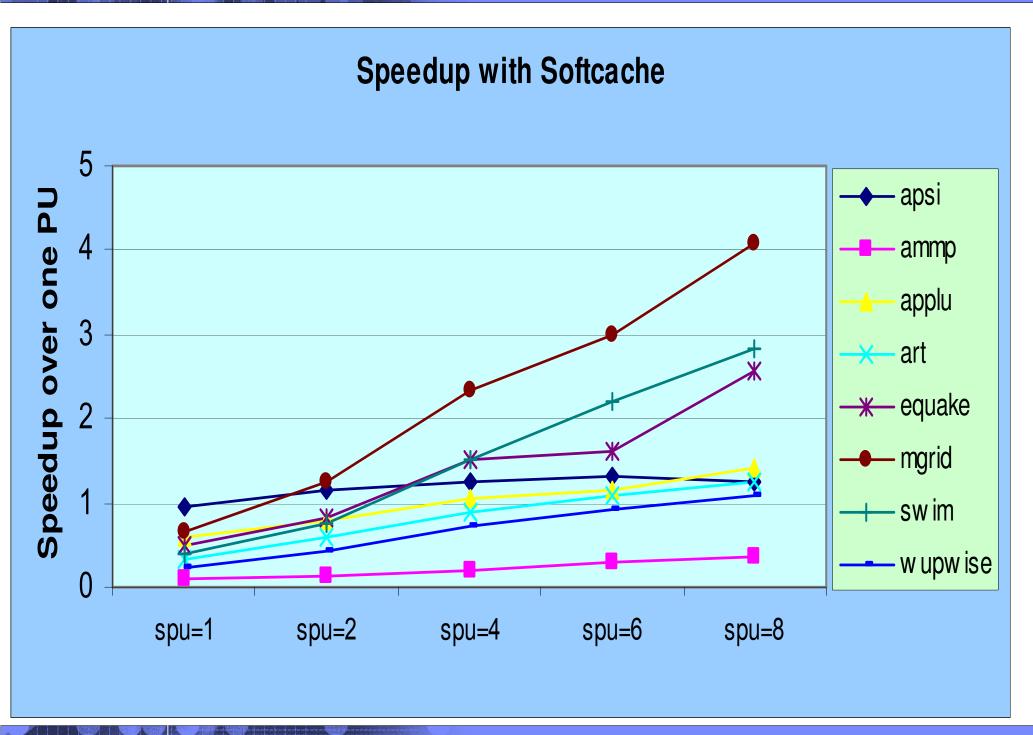
Single Source Compiler Results

□ Results for Swim, Mgrid, & some of their kernels



baseline: execution on one single PPE







Outline

Multiple-ISA hand-tuned

programs

Automatic tuning for each ISA

Part 3: **Automatic simdization**

Explicit SIMD coding

SIMD/alignment diredives

Automatic simulzation

Part 2:

Parallelization and memory abstraction

Explicit parallelization with

letetal eriperiera

Shared memory, single program abstraction

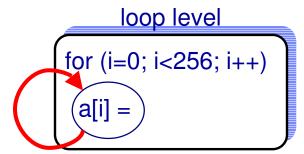
Automatic parallelization



Successful Simdizer

Extract Parallelism

Satisfy Constraints

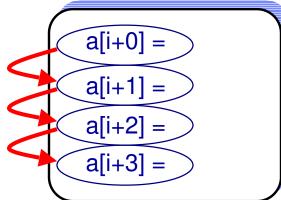


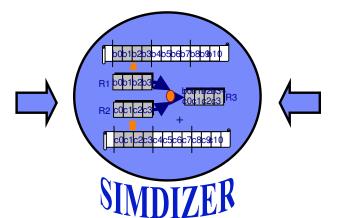




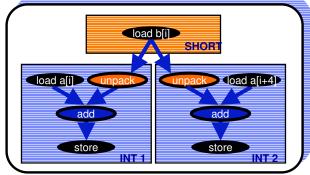
alignment constraints

basic-block level

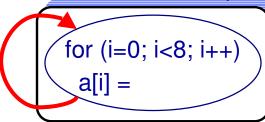


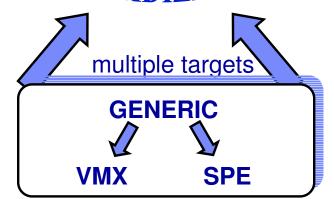




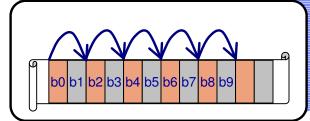


entire short loop





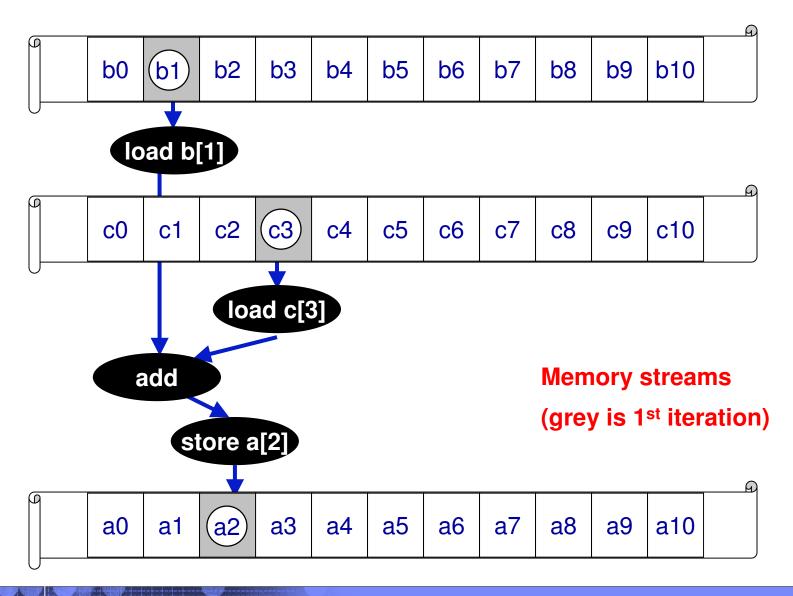
non stride-one





Traditional Execution of a Loop

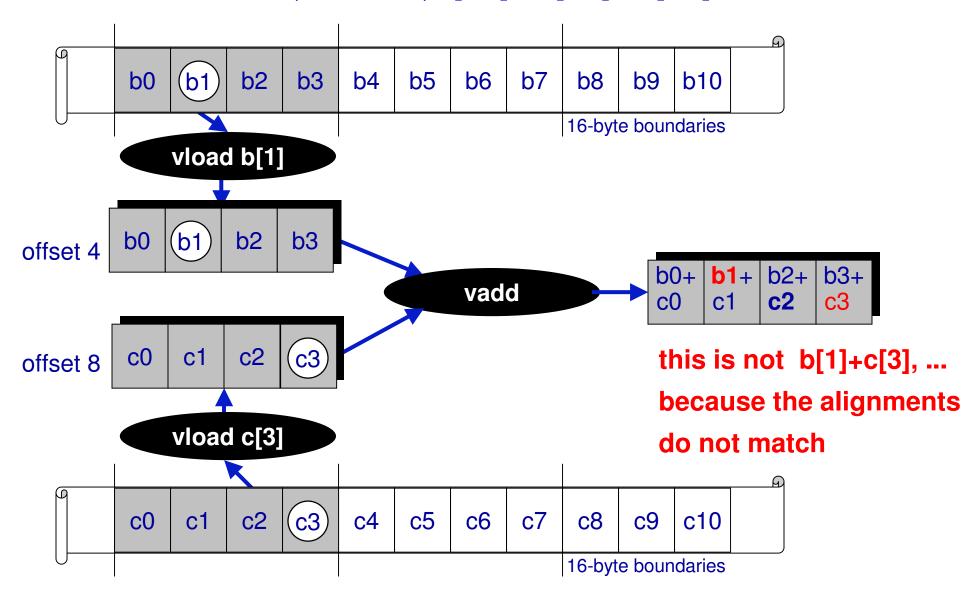
 \square Sequential execution of "for (i=0;i<64;i++) a[i+2] = b[i+1] + c[i+3]"





SIMD Alignment Problem

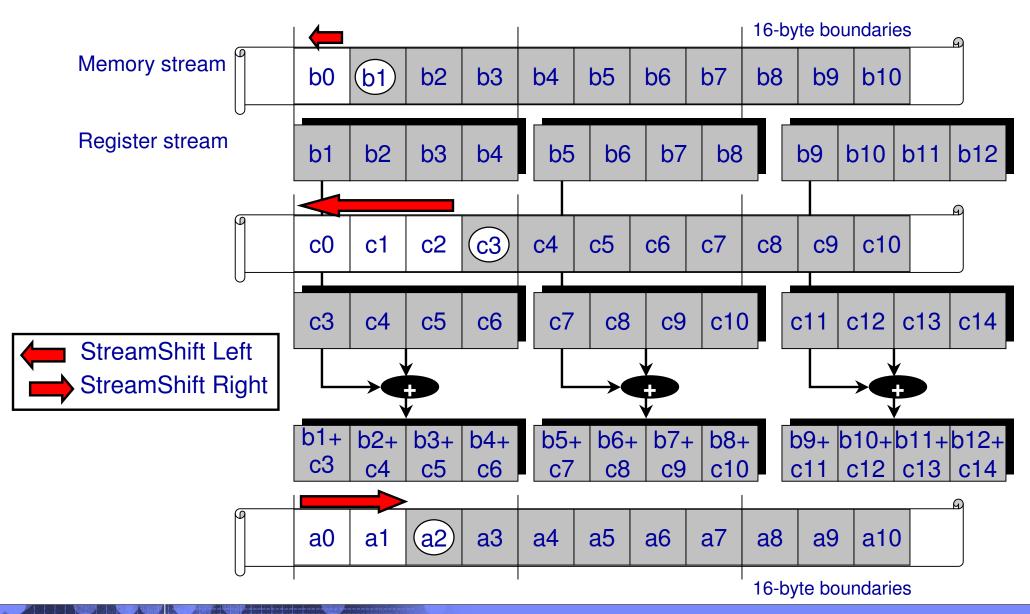
 \square SIMD execution of "for(i=0;i<64;i+) a[i+2] = b[i+1] + c[i+3]"





Loop-Level Simdization, Naïve Way

□ SIMD execution of "for(i=0;i<64;i+) a[i+2] = b[i+1] + c[i+3]"

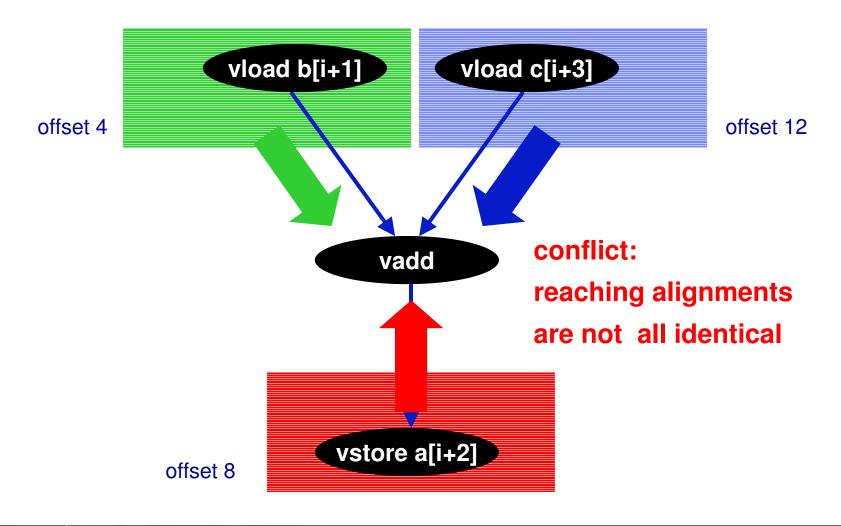




Solving the Alignment Problem

☐ Data Reorganization Graph

- original graph with alignment label each load/store
- resolve alignment conflicts

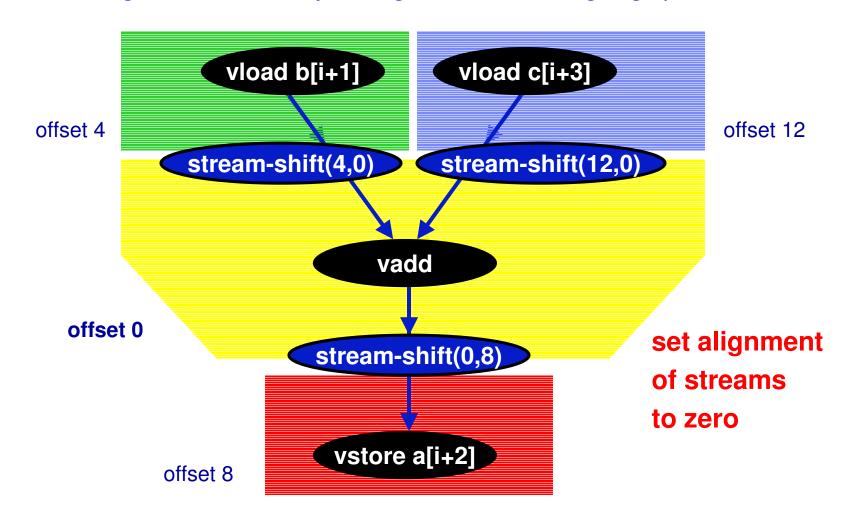




Solving the Alignment Problem

☐ Data Reorganization Graph

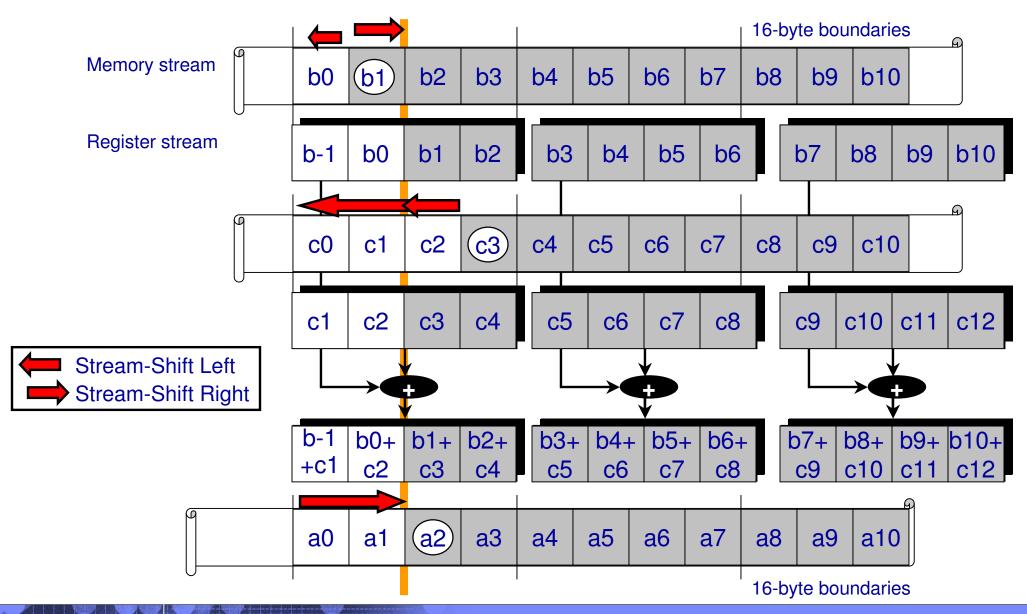
- original graph with alignment label each load/store
- resolve alignment conflicts by adding "stream-shift" aligning operations





Loop-Level Simdization, Optimized Way

□ SIMD execution of "for(i=0; i<64; i+) a[i+2] = b[i+1] + c[i+3]"

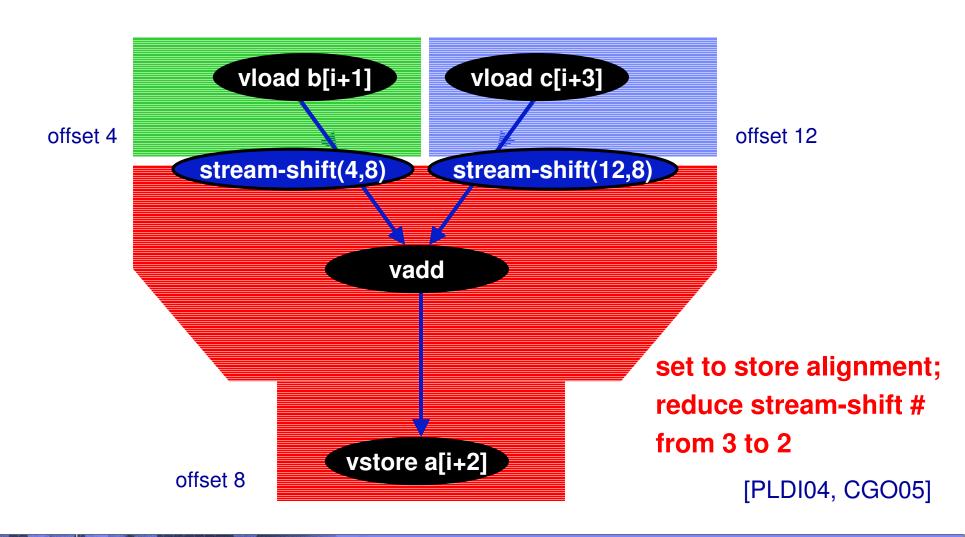




Optimized Solving of the Alignment Problem, Eager Policy

☐ Data Reorganization Graph

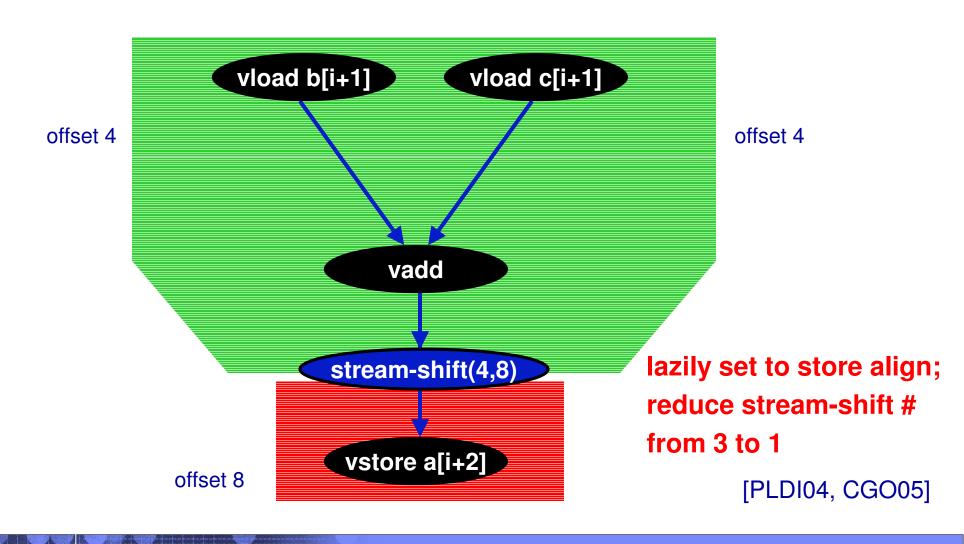
eagerly align to store alignment





Optimized Solving of the Alignment Problem, Lazy Policy

- □ Data Reorganization Graph (slightly different "b[i+1] + c[i+1]" example)
 - lazily align to store alignment





SIMD Code Generation

- ☐ SIMD codes are generated from a valid data reorganization graph
- □ Code generation for simdized loop

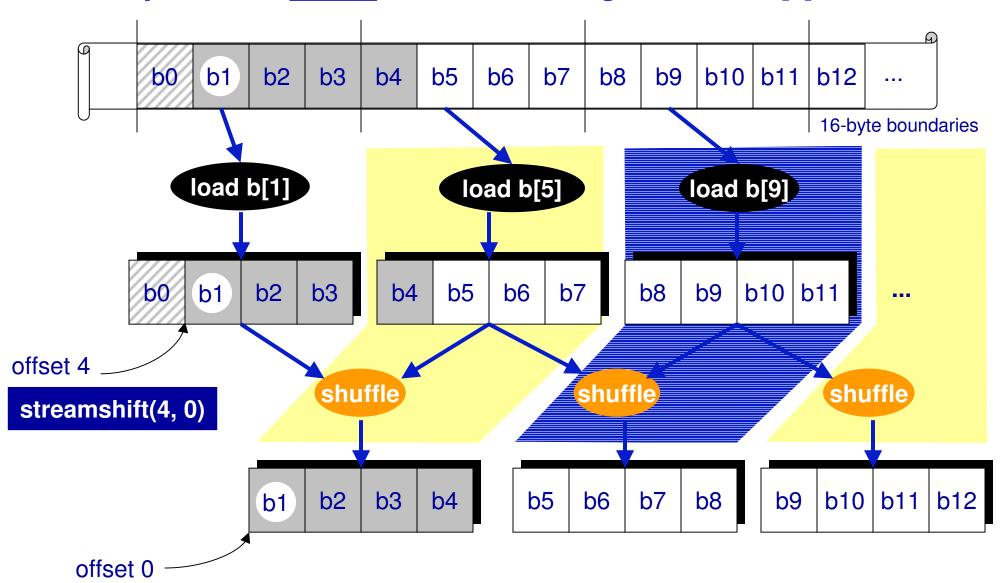
```
<simdized prologue>
for(i=0; i<100; i+=4)
     <simdized loop body>
<simdized epilogue>
```

- simdized loop (steady state)
- simdized prologue if store is misaligned
- simdized epilogue depending on store alignment and tripcount



Code Generation for Stream-Shift

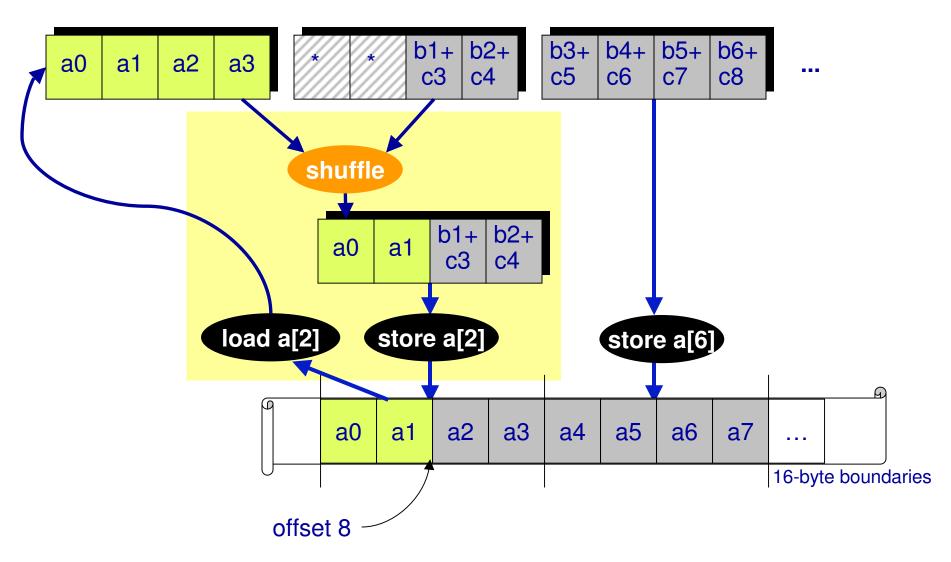
☐ When you need a <u>stream</u> of vectors starting at address b[1]





Code Generation for Partial Store

for (i=0; i<100; i++) a[i+2] = b[i+1] + c[i+3];





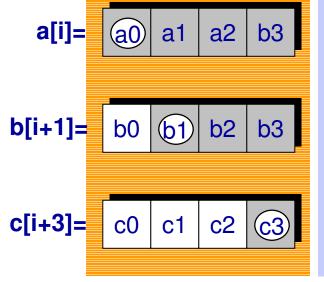
Code Generation for Loops (Multiple Statements)

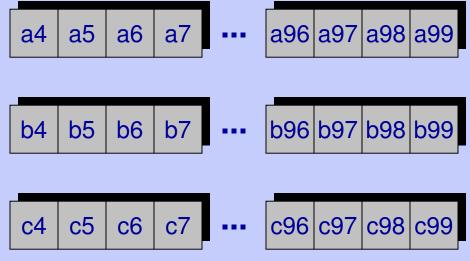
```
for (i=0; i<n; i++) {
   a[i] = ...;
   b[i+1] = ...;
   c[i+3] = ...;
}</pre>
```

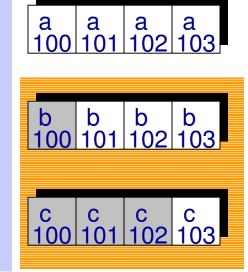
Implicit loop skewing (steady-state)

$$a[i+4] = ...$$

 $b[i+4] = ...$
 $c[i+4] = ...$







loop prologue (simdized)

loop steady state (simdized)

loop epilogue (simdized)



Machine-Independent Code After Simdization

☐ Pseudo codes after simdization (no software pipelining on adjacent loads)

- all operations are vectors
- loads/stores normalized to truncated address
- splice, shiftpairl, and shiftpairr are pseudo data reorganization operations to be mapped to spu_shuffle or spu_sel

```
 i = 0; \\ a[i] = splice(a[i], shiftpairr(b[i - 4], b[i], 4) + shiftpairl(c[i - 4], c[i], 4), 8); \\ do \{ \\ a[i + 4] = shiftpairr(b[i], b[i + 4], 4) + shiftpairl(c[i], c[i + 4], 4); \\ i = i + 4; \\ \} while (i < 95); \\ a[i + 4] = splice(shiftpairr(b[i], b[i + 4], 4) + shiftpairl(c[i], c[i + 4], 4), a[i + 4], 8)); \\
```



Machine-Dependent Intrinsic Codes after Simdization

```
□ after software pipelining, loop normalization, and address truncation □ spu_shuffle, spu_sel, spu_add, spu_mask are SPU intrinsics □ <0x08090a0b, ...> is a vector literal
```

```
a[0] = \text{spu\_sel}(a[0], \text{spu\_add}(\text{spu\_shuffle}(b[-4], b[0], <0x08090a0b, 0x0c0d0e0f, 0x10111213, 0x14151617>),
spu shuffle(c[-4],c[0], <0x0c0d0e0f,0x10111213,0x14151617,0x18191a1b>),spu maskb(15));
       oldSPCopy0 = c[0];
       oldSPCopy1 = b[0];
       i = 0:
       do {
         tc = c[i*4+4];
         tb = b[i*4+4];
         a[i*4+4] = spu_add(spu_shuffle(oldSPCopy1,tb,<0x08090a0b,0x0c0d0e0f,0x10111213,0x14151617>),
spu shuffle(oldSPCopy0, tc,<0x0c0d0e0f,0x10111213,0x14151617,0x18191a1b>);
         oldSPCopy0 = tc;
         oldSPCopy1 = tb;
         i = i + 1;
       } while (i < 24);
      a[100] = \text{spu sel(spu add(spu shuffle(b[96],b[100],<0x08090a0b,0x0c0d0e0f,0x10111213,0x14151617>)},
spu shuffle(c[96], c[100], <0x0c0d0e0f,0x10111213,0x14151617,0x18191a1b>), a[100], spu maskb(15));
```



Outline

□ Simdization example

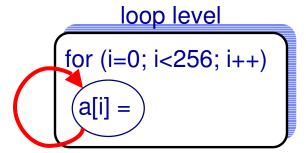
☐ Integrated simdization framework



Successful Simdizer

Extract Parallelism

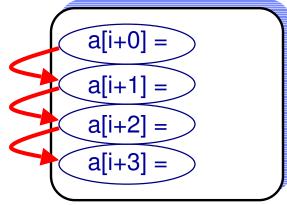
Satisfy Constraints

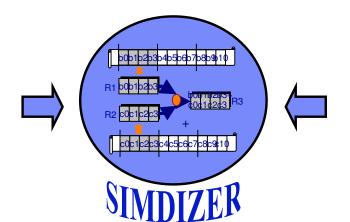






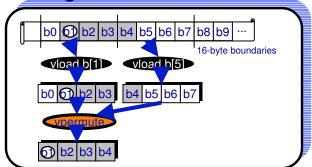
basic-block level



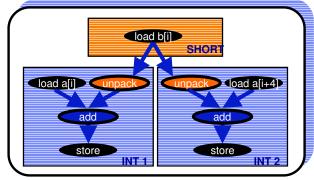


GENERIC VMX SPE

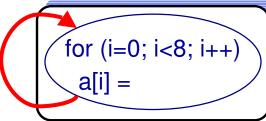
alignment constraints



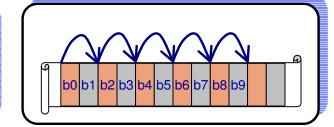
data size conversion



entire short loop

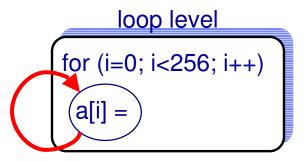


non stride-one





Multiple Sources of SIMD Parallelism



□ Loop level

- SIMD for a single statement across consecutive iterations
- > successful at:
 - efficiently handling misaligned data
 - pattern recognition (reduction, linear recursion)
 - leverage loop transformations in most compilers
 - amortize overhead (versioning, alignment handling) and employ cost models

[Bik et al, IJPP 2002]

[VAST compiler, 2004]

[Eichenberger et al, PLDI 2004] [Wu et al, CGO 2005]

[Naishlos, GCC Developer's Summit 2004]



Multiple Sources of SIMD Parallelism (cont.)

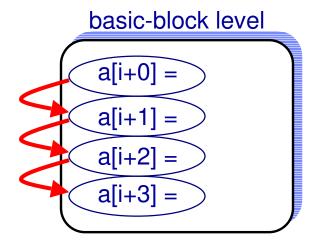
□ Basic-block level

- SIMD across multiple isomorphic operations
- > successful at
 - handling unrolled loops (manually or by compiler)
 - extracting SIMD parallelism within structs, e.g.

extracting SIMD parallelism within a statement

$$s += a(i)*b(i) + a(i+1)*b(i+1) + a(i+2)*b(i+2) + a(i+3)*b(i+3) + a(i+4)*b(i+4)$$

[Larsen et al, PLDI 2000] [Shin et al, PACT 2002]





Multiple Sources of SIMD Parallelism (cont.)

□ Short-loop level

- > SIMD across entire loop iterations
- effectively collapse innermost loop
- we can now extract SIMD at the next loop level
- > e.g. FIR

```
for (k=0; k<248; k++)

for (i=0; i<8; i++)

res[k] += in[k+i] * coef[k+i];
```

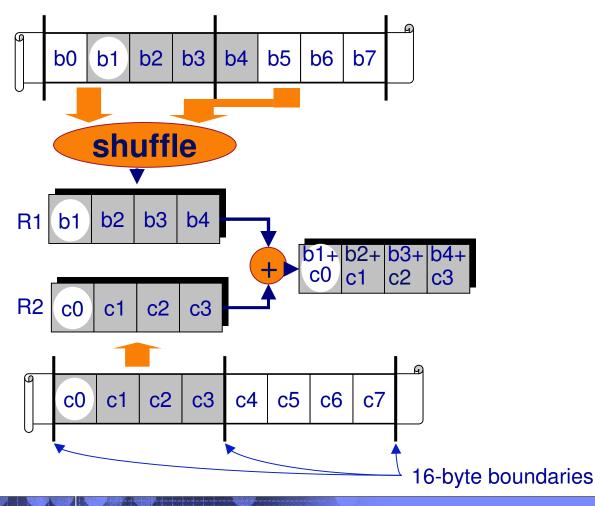
entire short loop for (i=0; i<8; i++) a[i] =

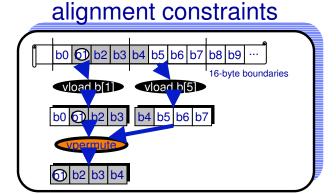


Multiple SIMD Hardware Constraints

□ Alignment in SIMD units matters

- when alignments within inputs do not match
- > must realign the data

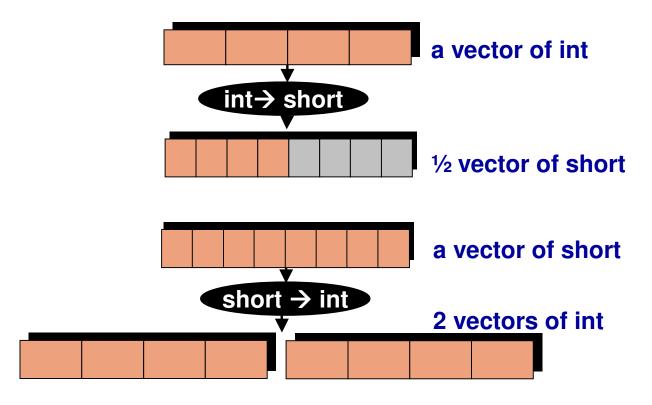


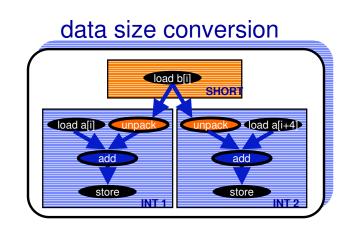




Multiple SIMD Hardware Constraints (cont.)

□ Size of data in SIMD registers matters



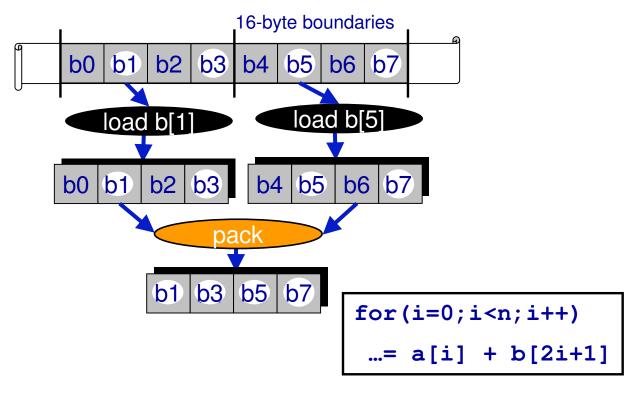


- ☐ E.g. when converting from short to integer.
 - we must issue 2x integer SIMD operations

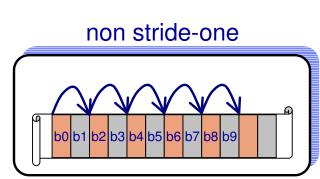


Multiple SIMD Hardware Constraints (cont.)

- ☐ Hardware supports 16-byte continuous access only
- Non stride-one load requires packing



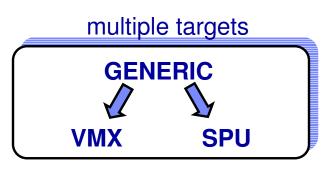
■ Non stride-one store requires unpacking





Multiple SIMD Hardware Constraints (cont.)

- □ Different platforms have varying SIMD support
 - > e.g. VMX / SPE have SIMD permute instructions
 - > e.g. SPE has no memory page fault, VMX does





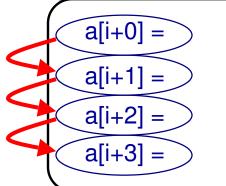
Extract Parallelism How to support the cross Satisfy Constraints product of all these?

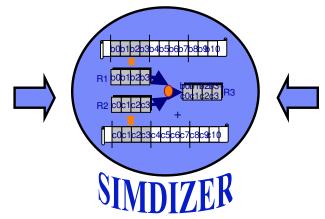
loop level



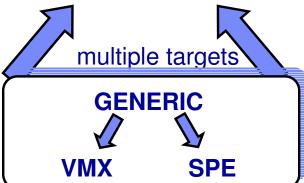


basic-block level

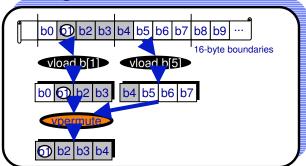




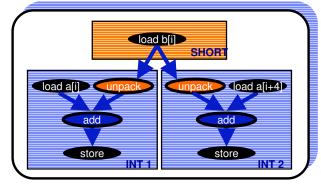
entire short loop



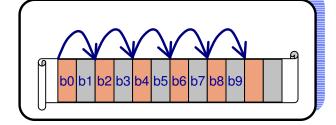
alignment constraints



data size conversion



non stride-one



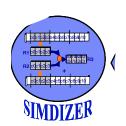


Key Abstraction: Virtual SIMD Vector

- □ Virtual SIMD Vector
 - >has arbitrary length
 - ➤ has no alignment constraints
- ☐ Extraction of SIMD Parallelism
 - >use virtual vector as representation
 - ➤ abstract away all the hardware complexity

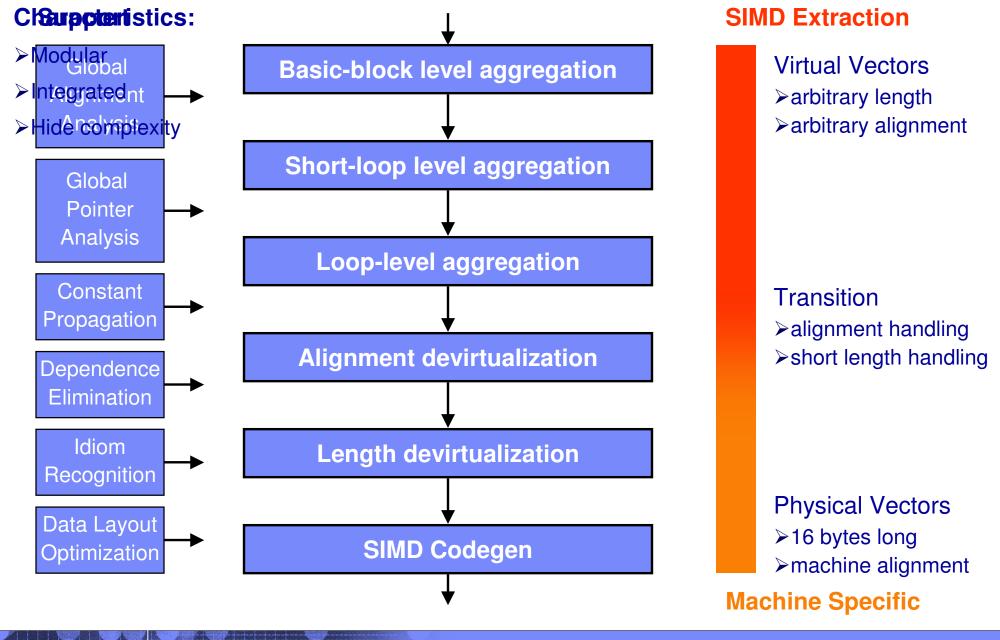


- >until each vector in the loop satisfies all hardware constraints
- ➤or revert vectors back to scalars (if too much overhead)



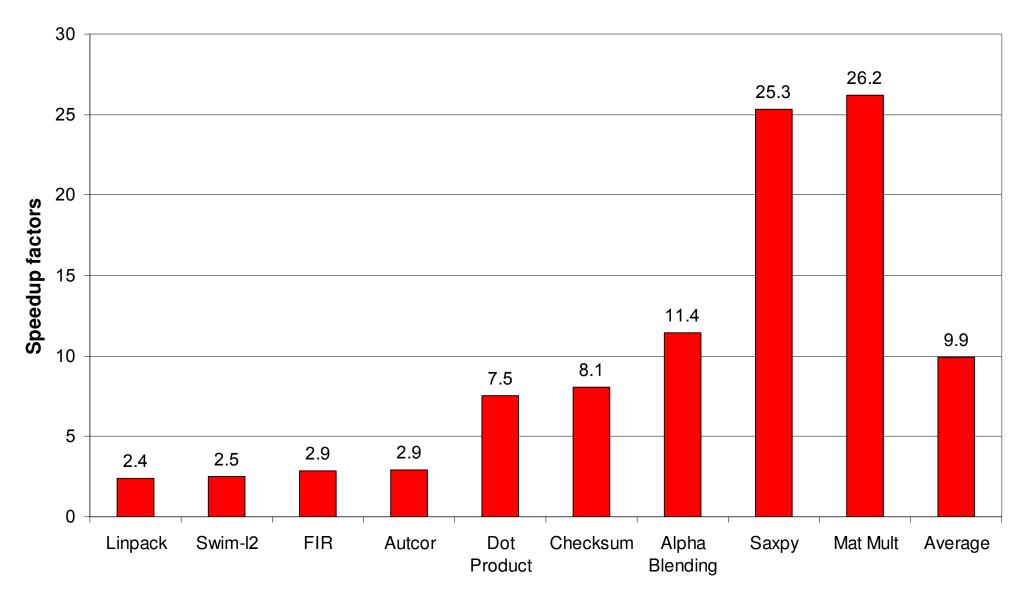


Integrated Simdization Framework





SPE Simdization Results



single SPE, optimized, automatic simdization vs. scalar code



Conclusions

□ Cell Broadband Engine architecture

- heterogeneous parallelism
- dense compute architecture

☐ Present the application writer with a wide range of tool

- from support to extract maximum performance
- to support to achieve maximum productivity with automatic tools

☐ Shown respectable speedups

using automatic tuning, simdization, and support for shared-memory abstraction



Questions

For additional info:

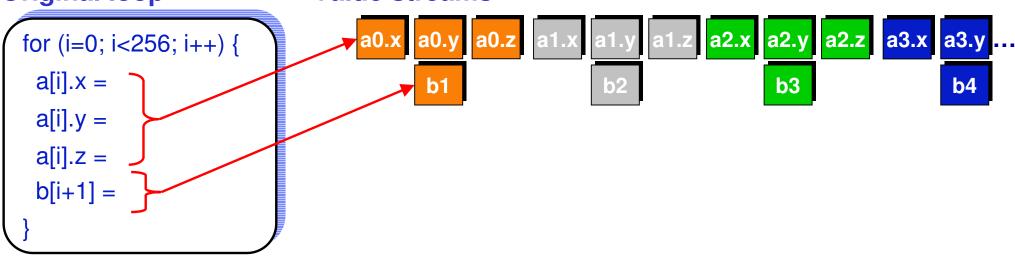
www.research.ibm.com/cellcompiler/compiler.htm



First Example: Basic-Block & Loop Level Aggregation

Original loop

Value streams



4 iterations shown here for the purpose of illustration





Phase 1: Basic-Block Level Aggregation

Original loop Value streams for (i=0; i<256; i++) {</td> a0.x a0.y a0.z a1.x a1.y a1.z a2.x a2.y a2.z a3.x a3.y ... b[i+1] = b1 b2 b3 b4

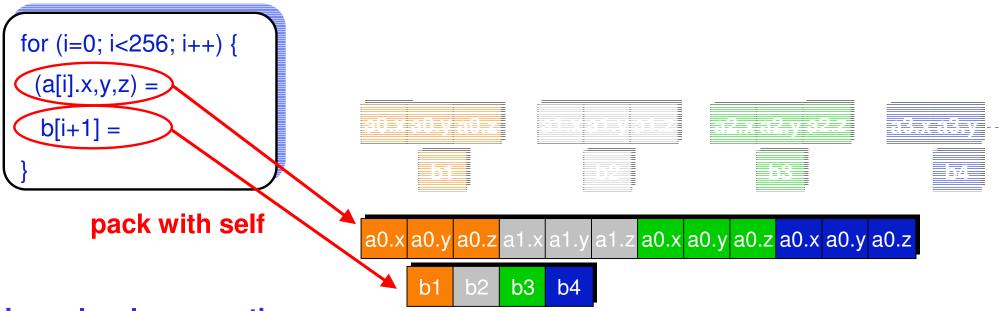
Basic-Block level aggregation

- > pack a[i].x, a[i].y, a[i].z into a vector of 3 elements
- pack regardless of alignment



Phase 2: Loop-Level Aggregation

BB-aggregated loop Value streams



Loop-level aggregation

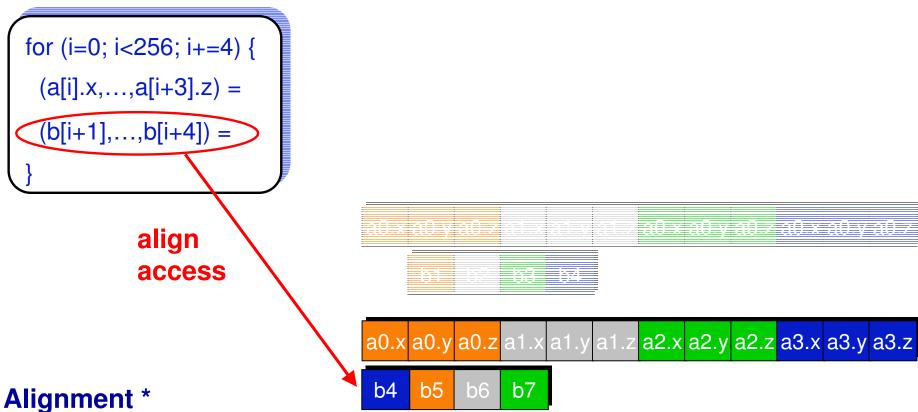
- > pack each statement with itself across consecutive iterations
- > final vector lengths must be multiple of 16 bytes
- scalar "b[i]" or vector "(a[i].x,y,z)" are treated alike
- pack regardless of alignment



Phase 3: Alignment Devirtualization

Loop-aggregated

Value streams



- ➤ shift misaligned streams
- >skew the computations so that loop computes (b[i+4]...b[i+7])

^{*} Arrays (e.g. &a[0], &b[0],...) are assumed here 16-byte aligned.



Phase 4: Length Devirtualization

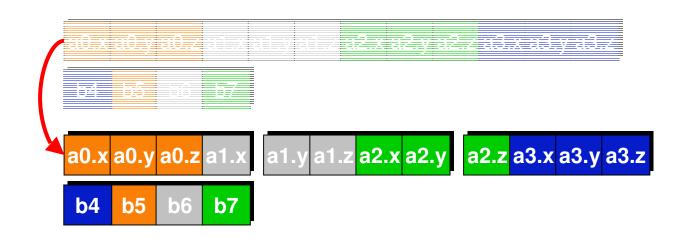
Aligned loop

(b[1]...b[3]) = for (i=0; i<252; i+=4) { (a[i].x,...,a[i+3].z) = (b[i+4],...,b[i+7]) = } (a[252].x,...,a[255].z) = b[256] =

Value streams

Length

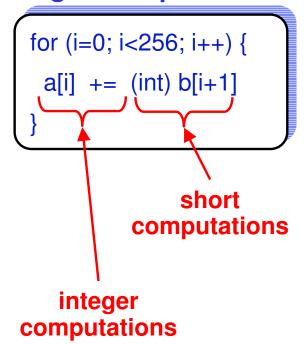
➤ break into 16-byte chunks

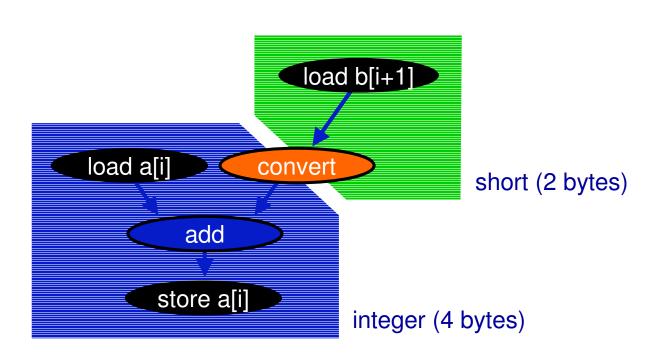




Second Example: Data-Size Conversion and Misalignment

Original loop

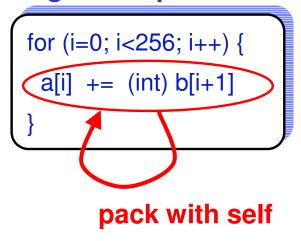


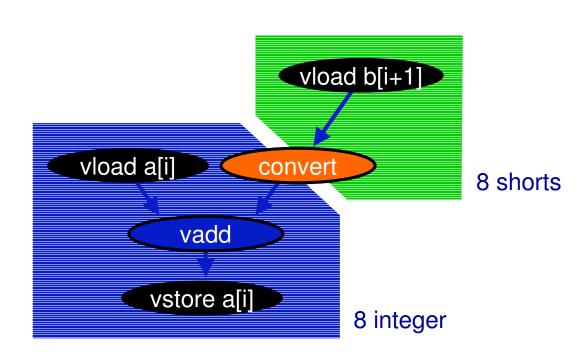




Phase 1: Loop-Level Aggregation

Original loop





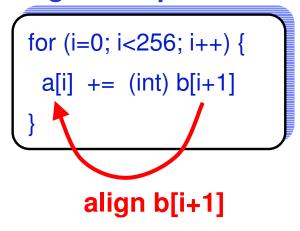
Loop-level aggregation

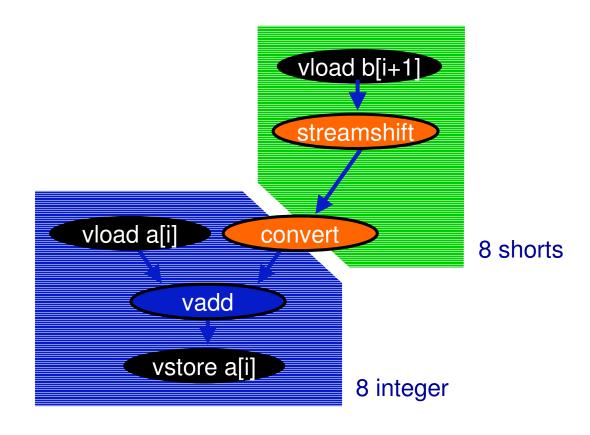
- pack each statement with itself across consecutive iterations
- virtual vectors have uniform number of elements, even when
 - vector of 8 integer = 32 bytes of data
 - vector of 8 short = 16 bytes of data



Phase 2: Alignment Devirtualization

Original loop





Alignment

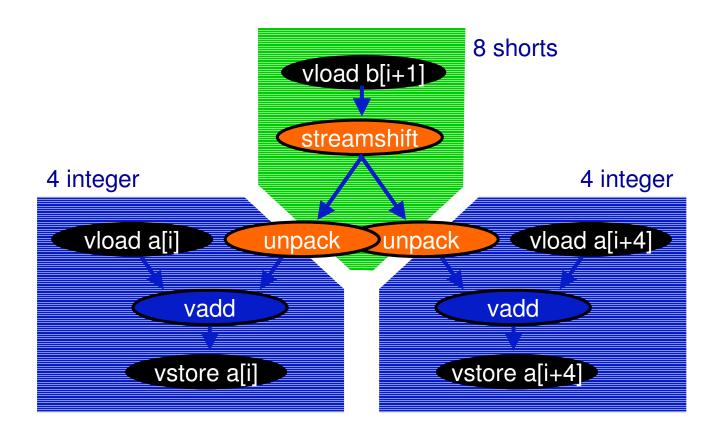
- shift misaligned streams
- easy to do as we are still dealing with long vectors



Phase 3: Length Devirtualization

Original loop

```
for (i=0; i<256; i++) {
    a[i] += (int) b[i+1]
}
```



Length

- > 8 shorts fit into a 16-byte register
- 8 integers do not fit; must replicate integer registers and associated instructions